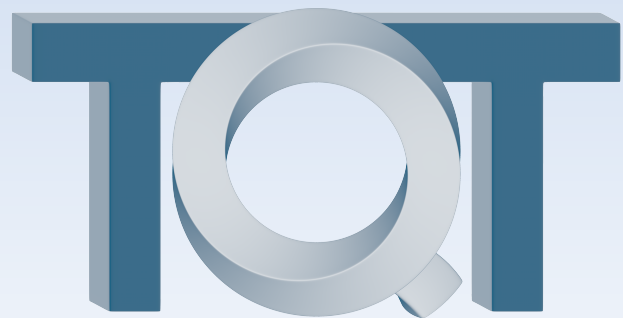


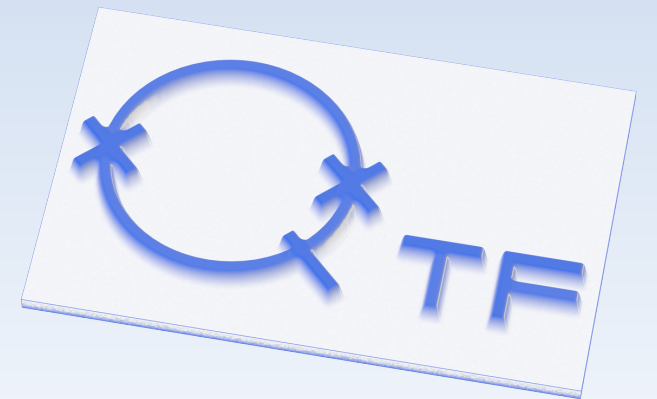
# Noise-disturbance relation and the Galois connection of quantum measurements



Turku Quantum Technology

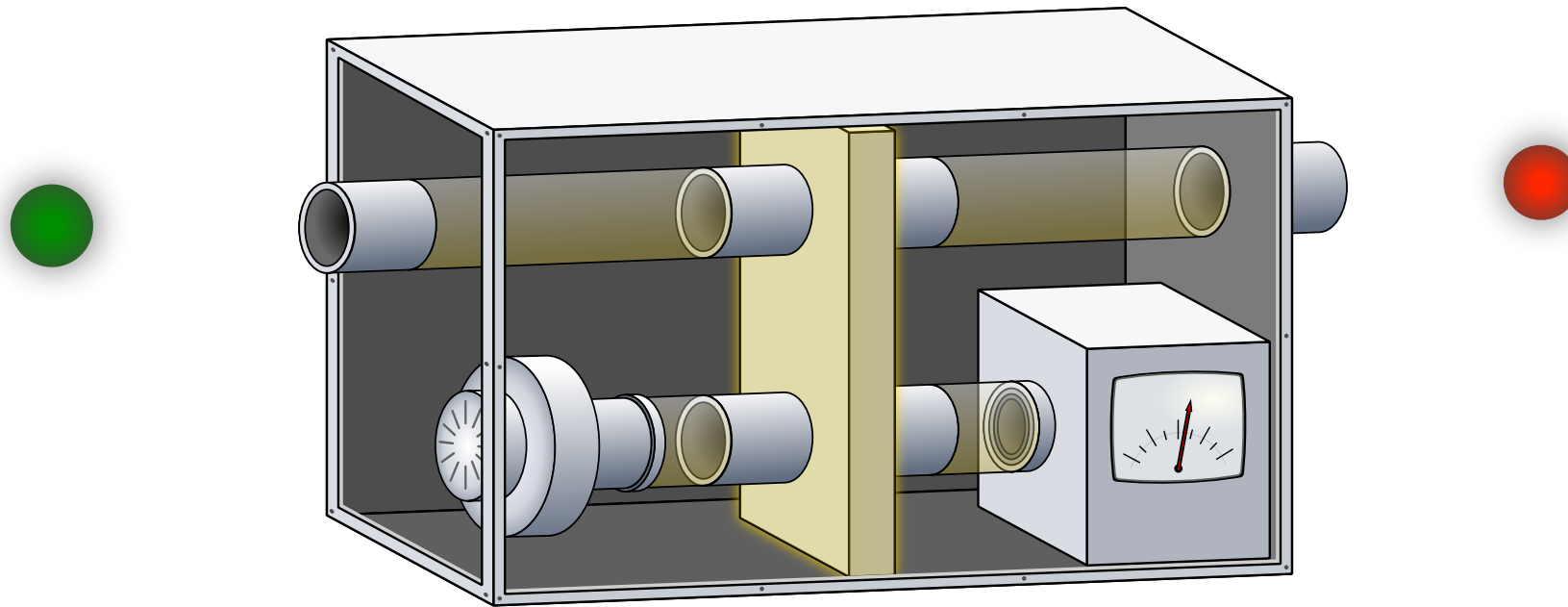
*Teiko Heinosaari*

*University of Turku  
Finland*



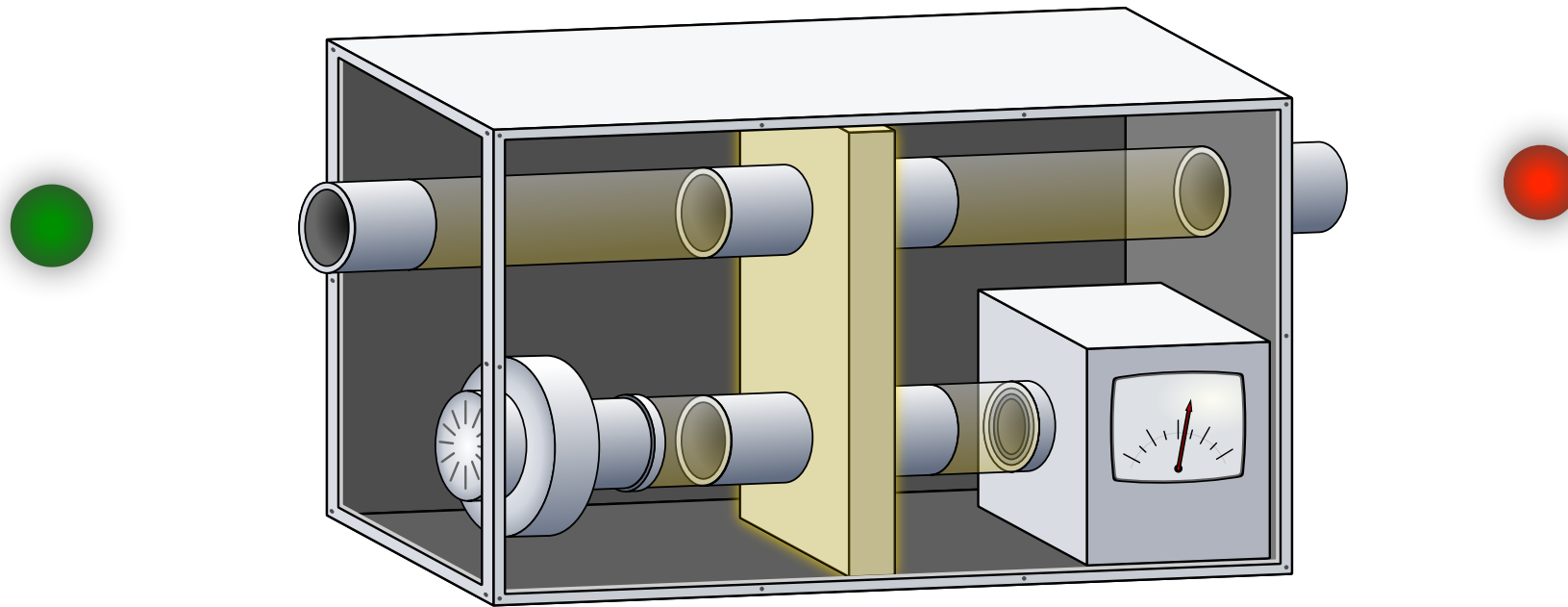
Quantum Technology Finland

# noise-disturbance tradeoff



$$\textit{noise} \cdot \textit{disturbance} \geq 1$$

# noise-disturbance tradeoff

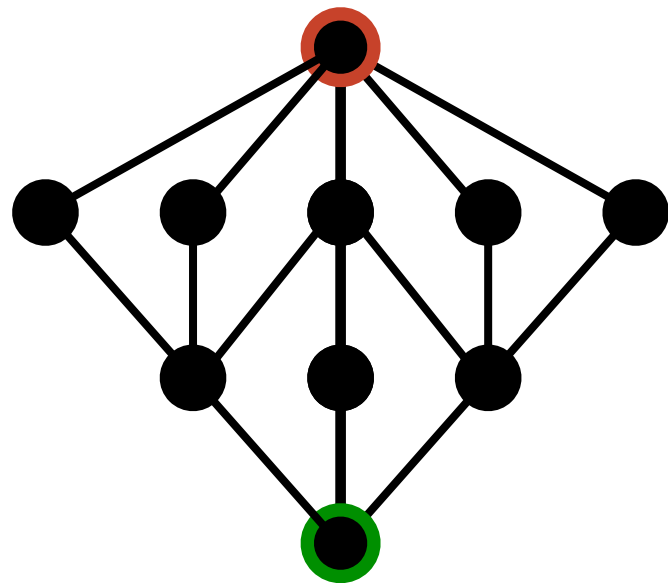


$$\textit{noise} \cdot \textit{disturbance} \geq 1$$

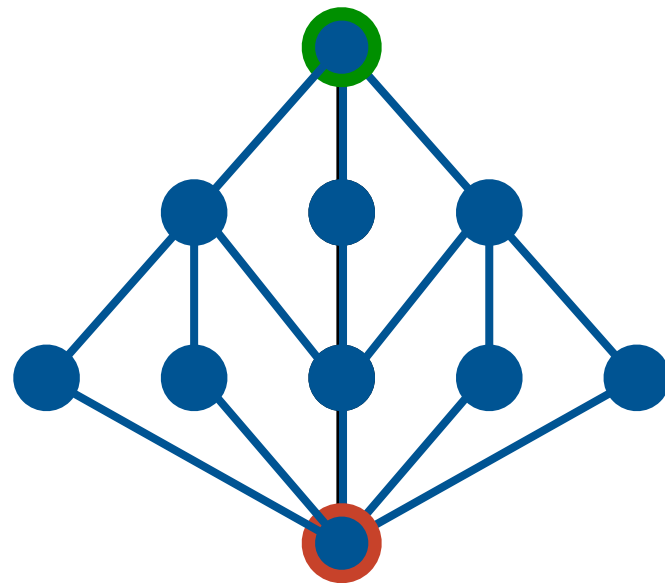
structural relation?

# Galois theory

fields



groups



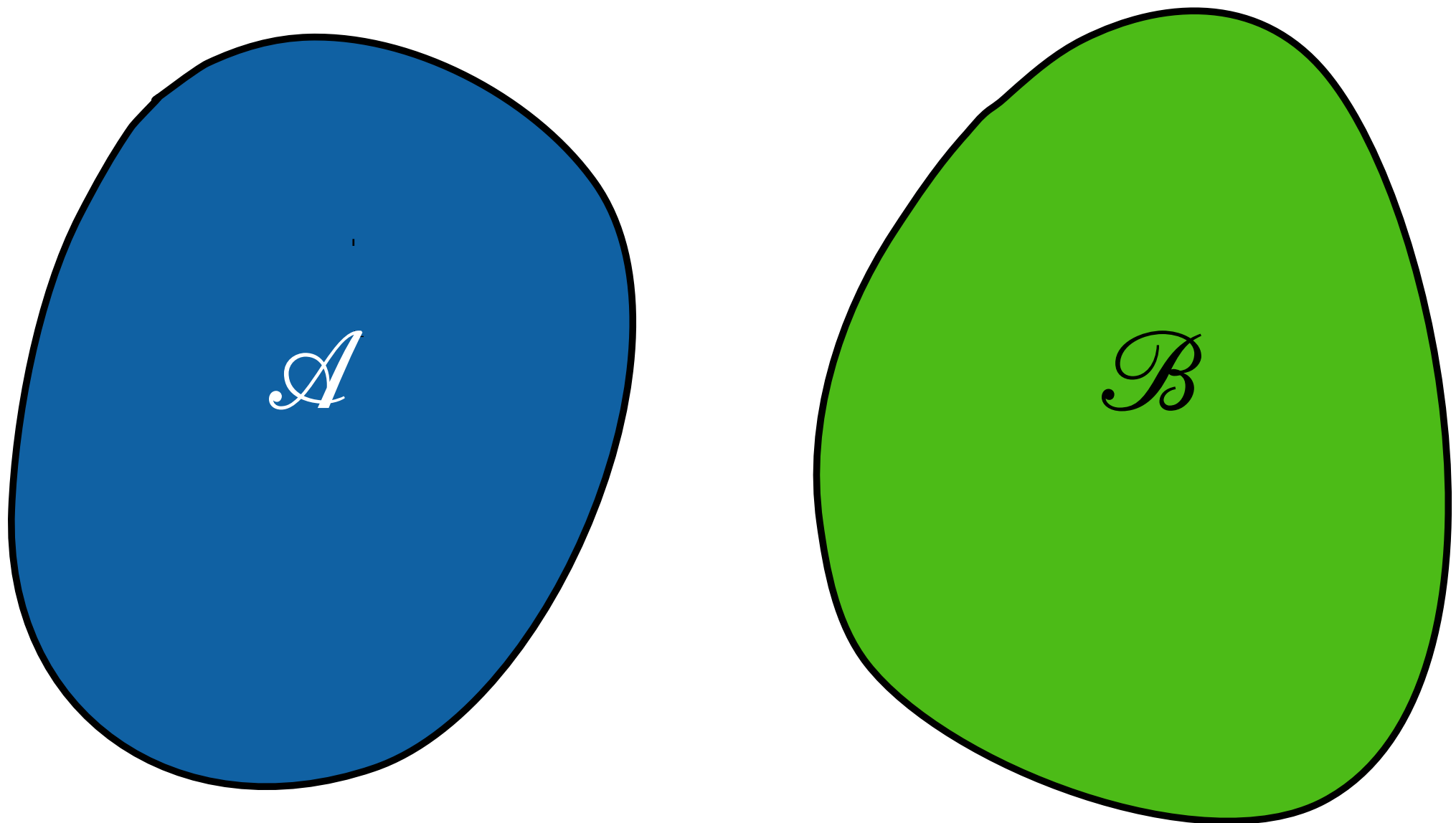
inverse relation



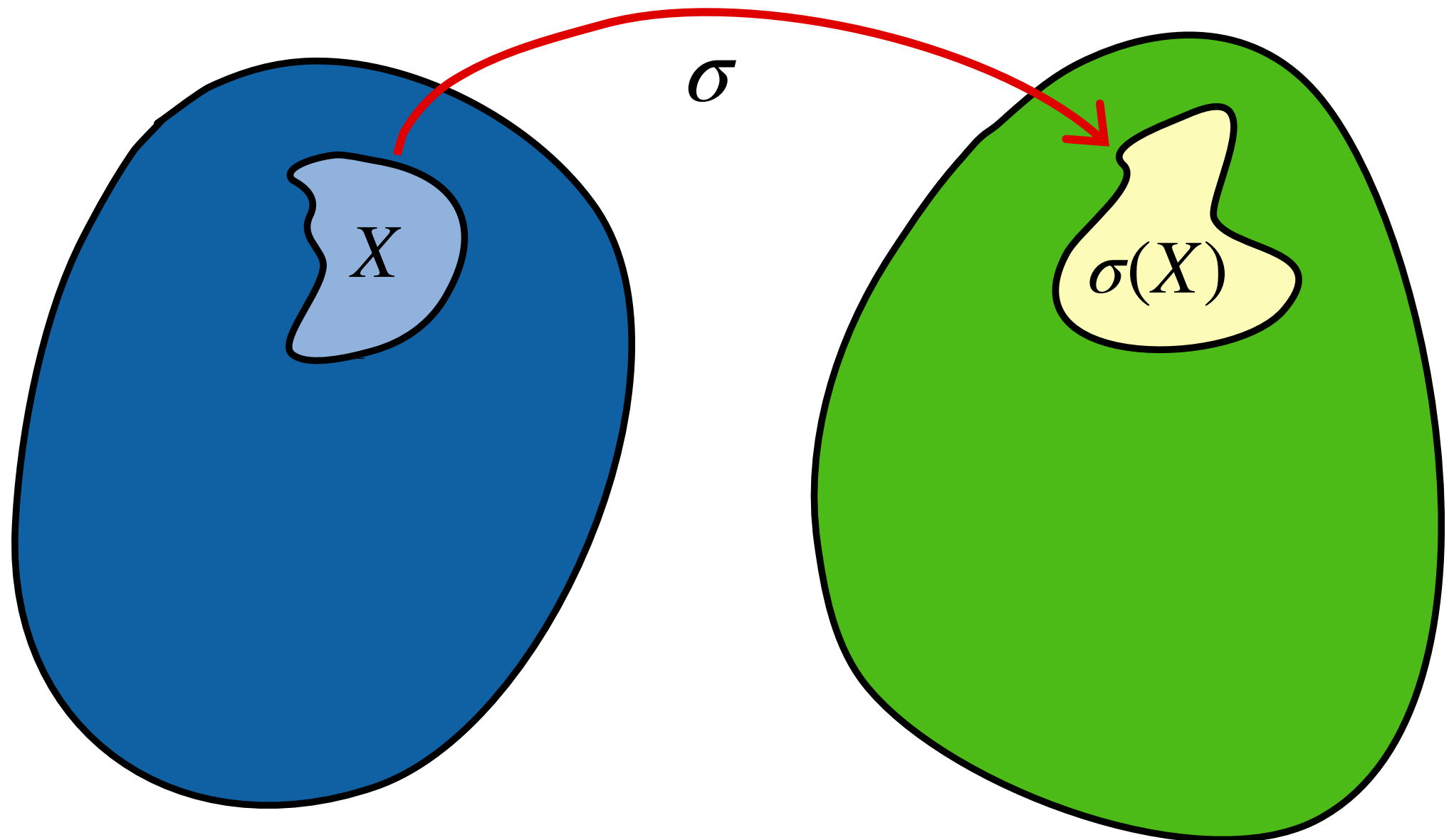
Évariste Galois  
1811-1832



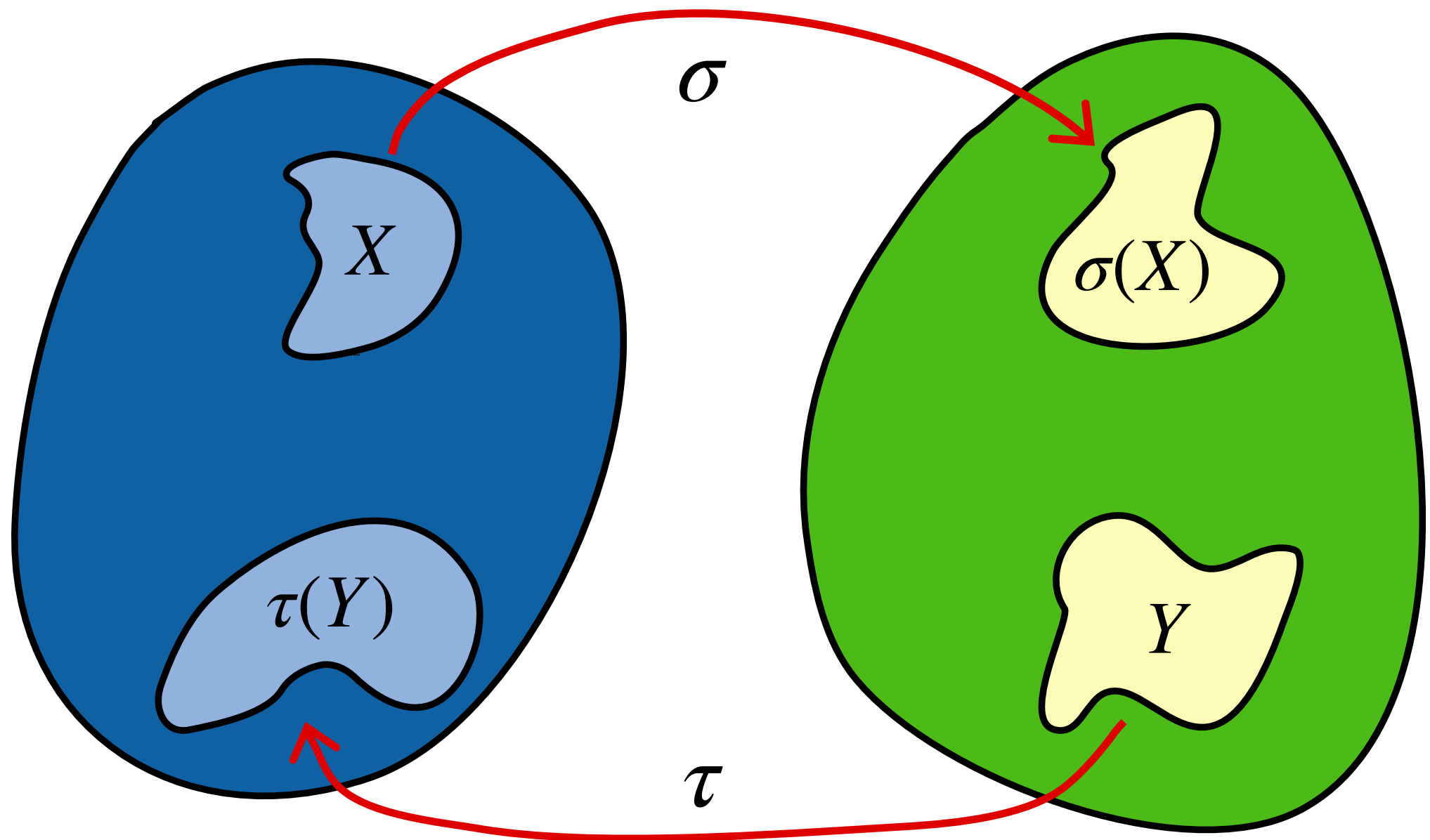
# Galois connection



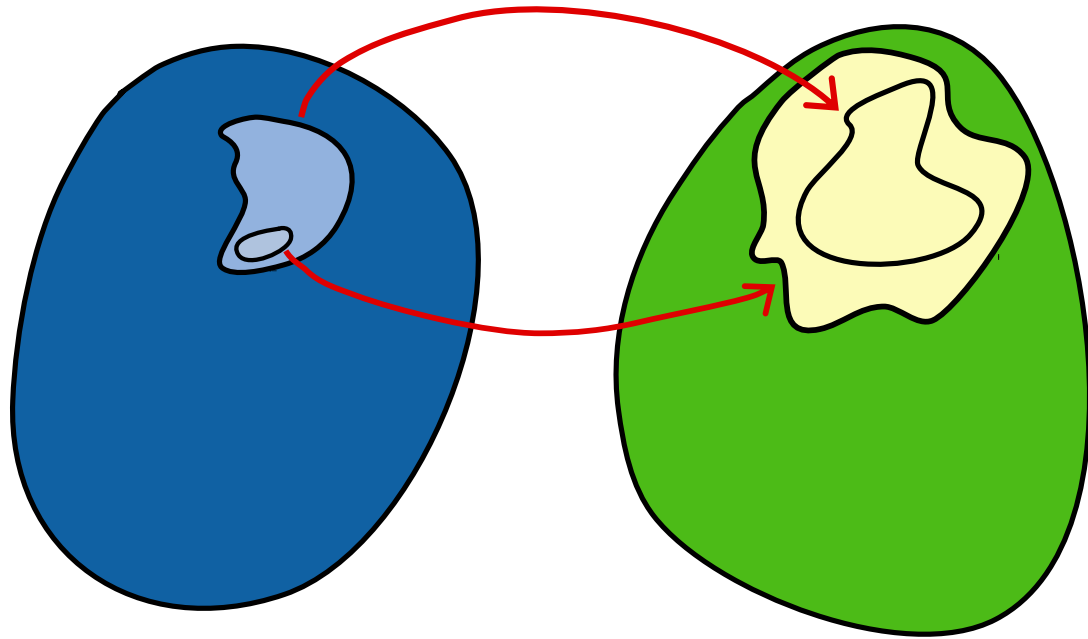
# Galois connection



# Galois connection



# Galois connection

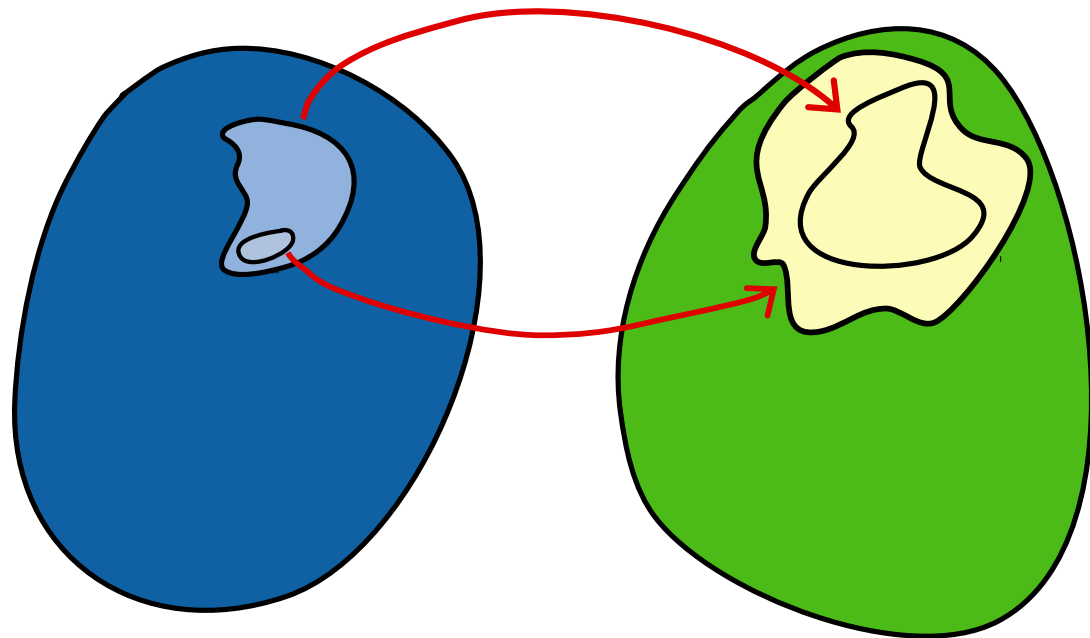


❖ **Condition 1**

$$X' \subseteq X \Rightarrow \sigma(X') \supseteq \sigma(X)$$

$$Y' \subseteq Y \Rightarrow \tau(Y') \supseteq \tau(Y)$$

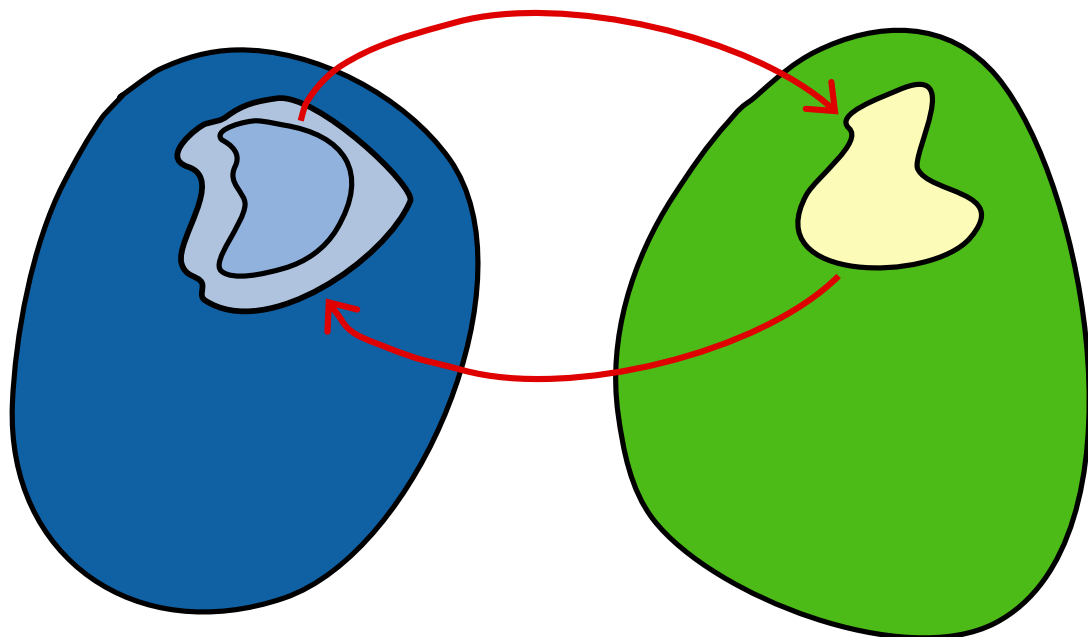
# Galois connection



## ❖ Condition 1

$$X' \subseteq X \Rightarrow \sigma(X') \supseteq \sigma(X)$$

$$Y' \subseteq Y \Rightarrow \tau(Y') \supseteq \tau(Y)$$



## ❖ Condition 2

$$X \subseteq \tau(\sigma(X))$$

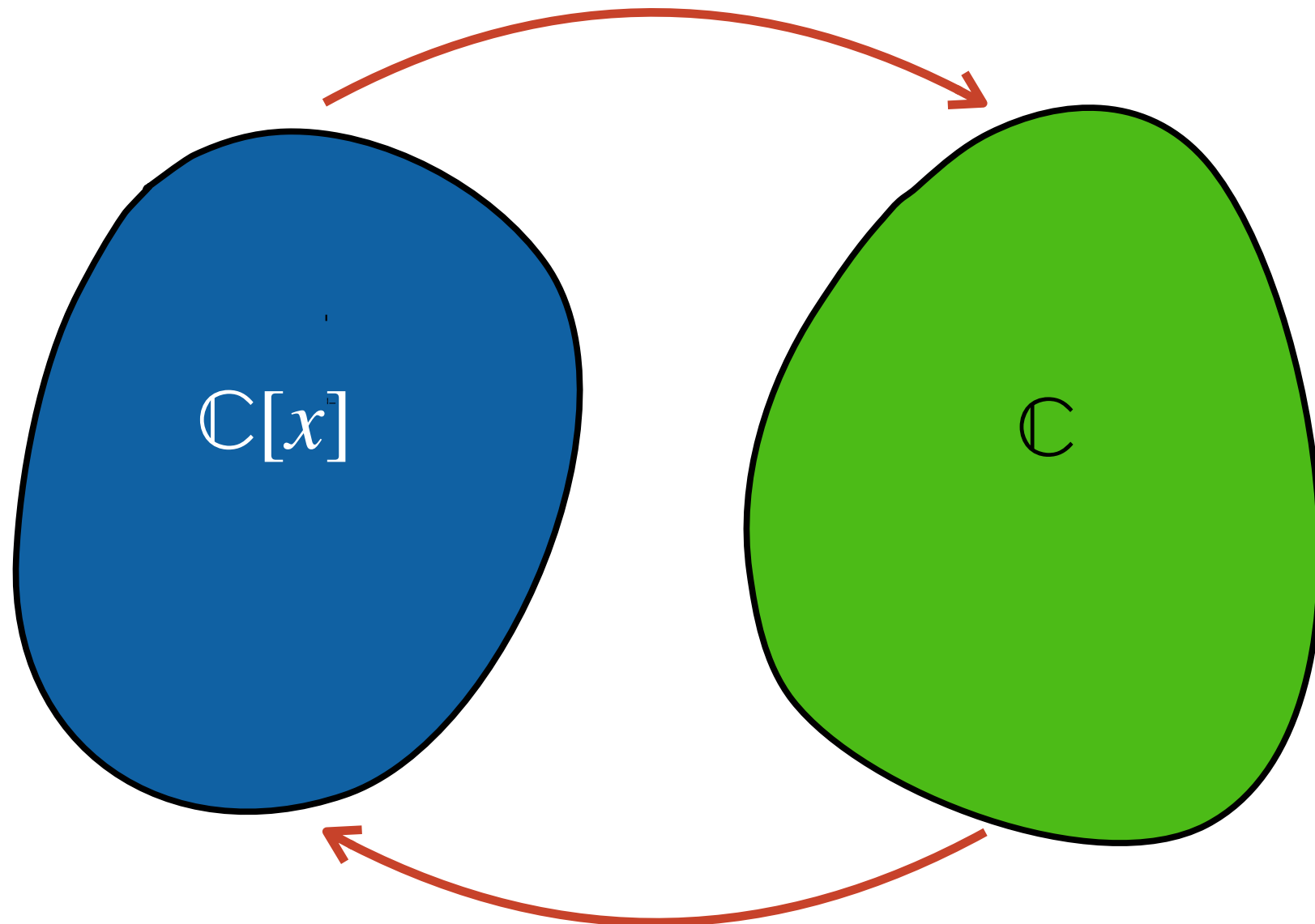
$$Y \subseteq \sigma(\tau(Y))$$



# Galois connection

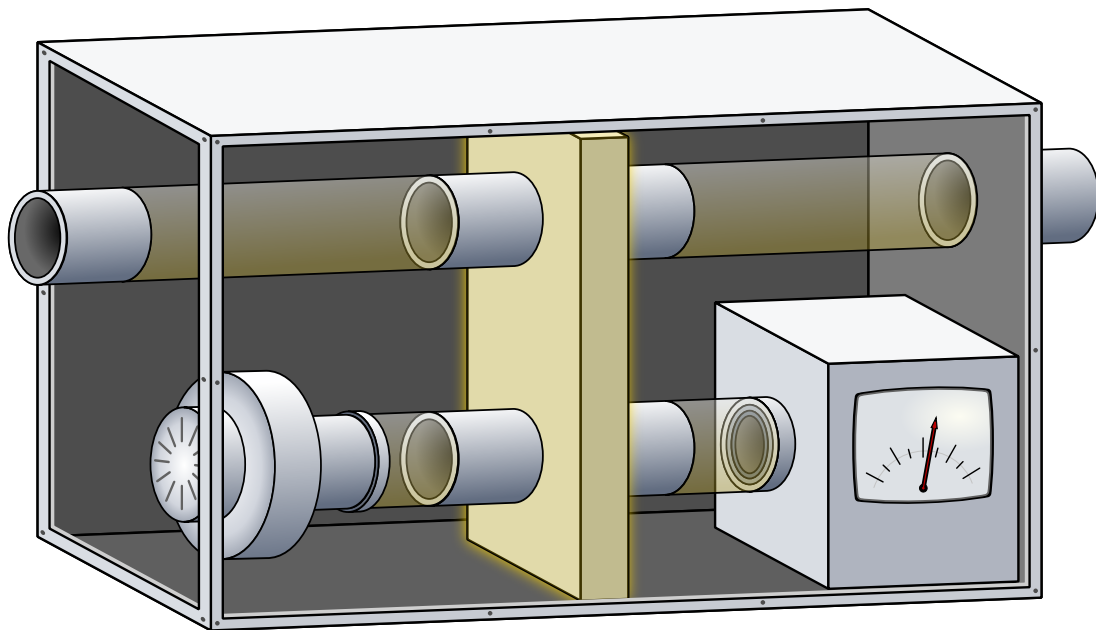
## Example

$$\sigma(X) = \{c \in \mathbb{C} : f(c) = 0 \ \forall f \in X\}$$

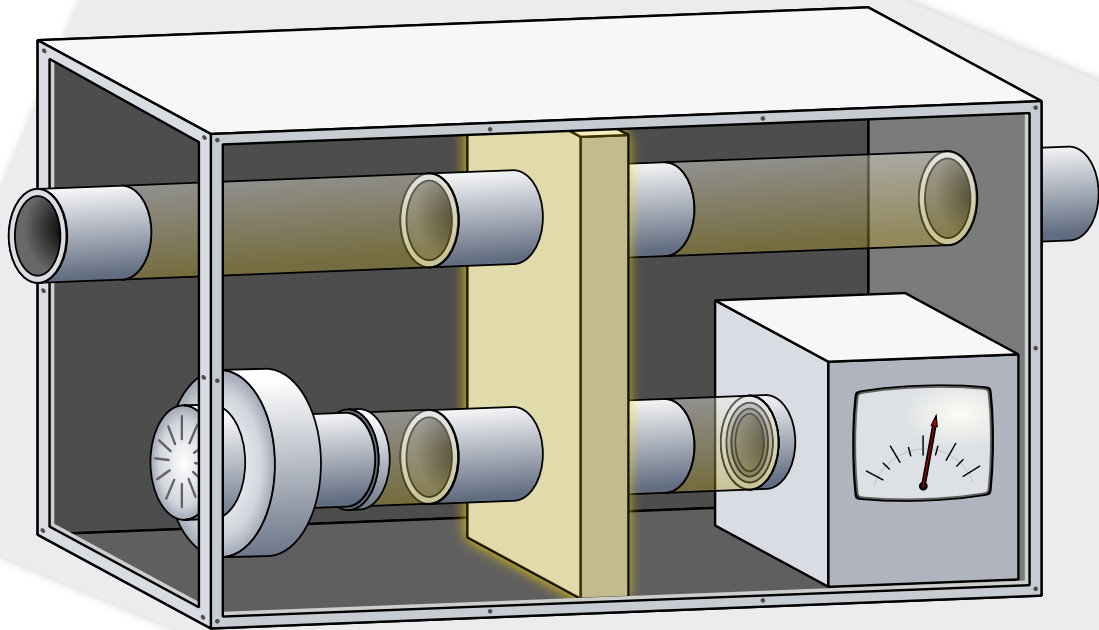


$$\tau(Y) = \{f \in \mathbb{C}[x] : f(c) = 0 \ \forall c \in Y\}$$

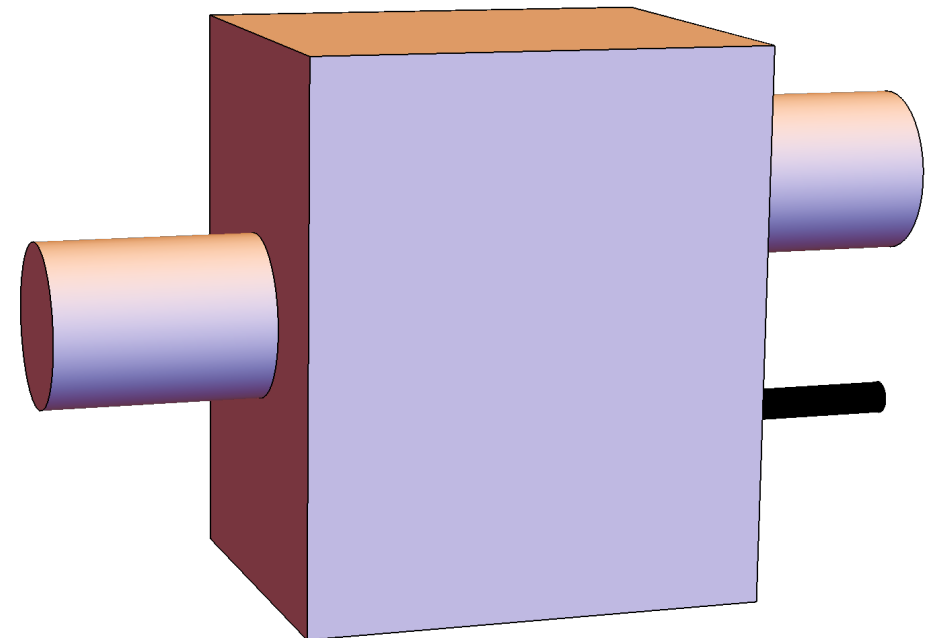
# quantum measurements



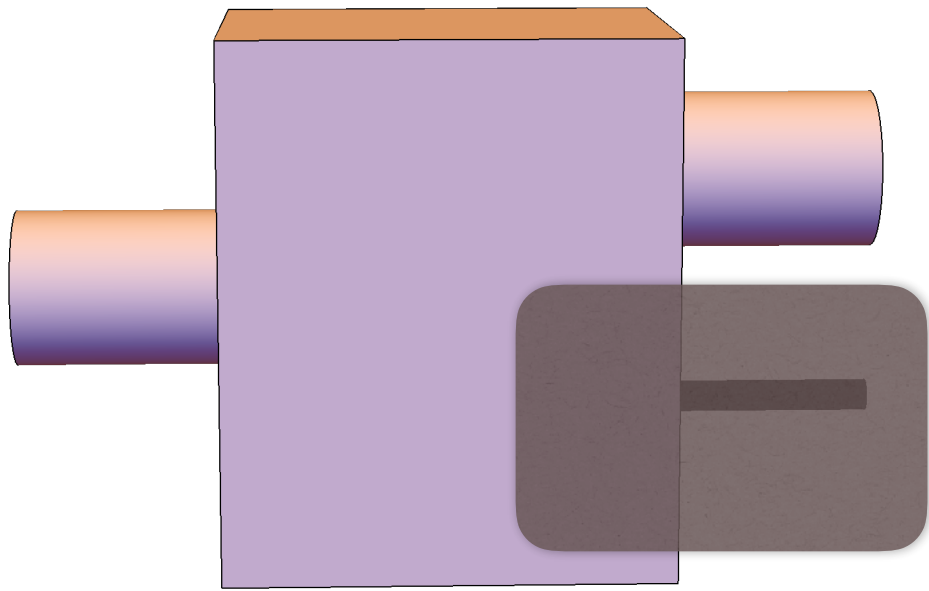
# quantum measurements



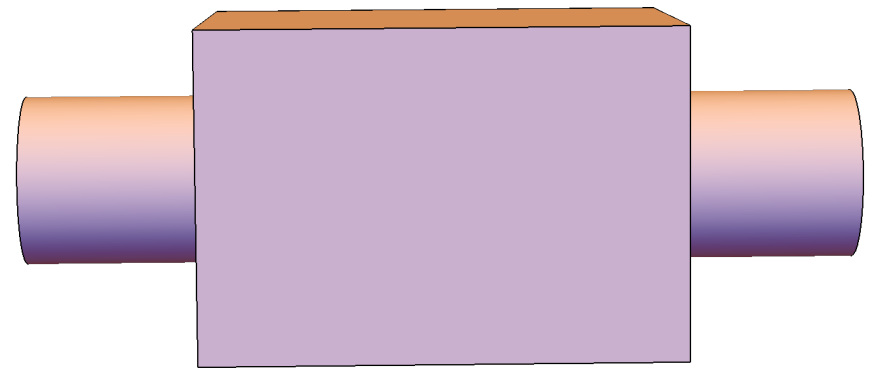
quantum  
instrument



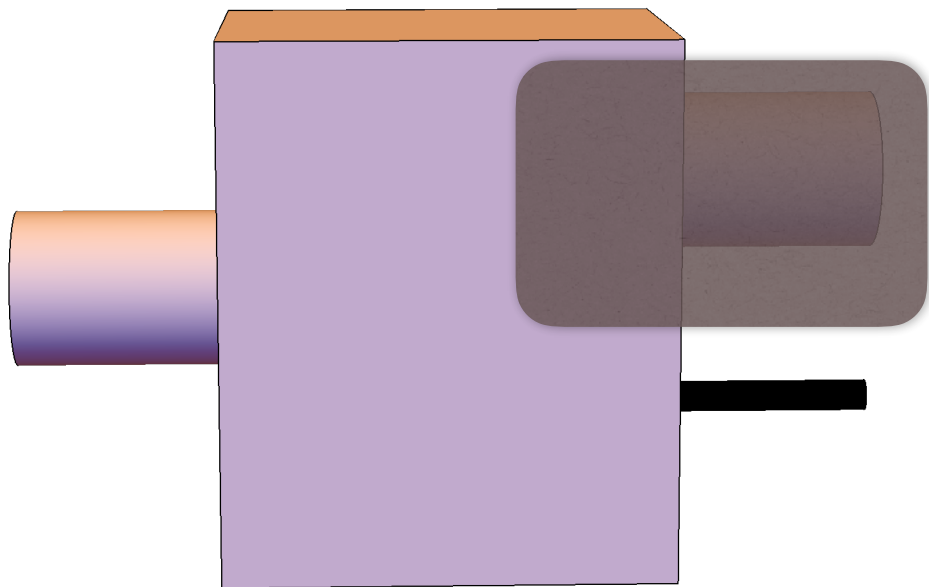
# channels and observables



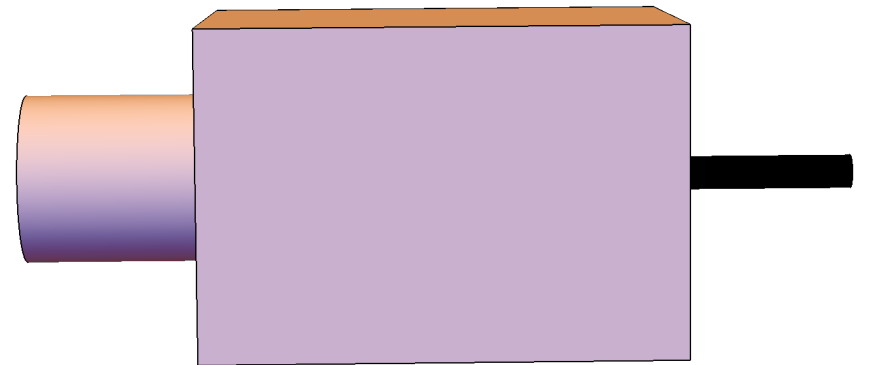
=



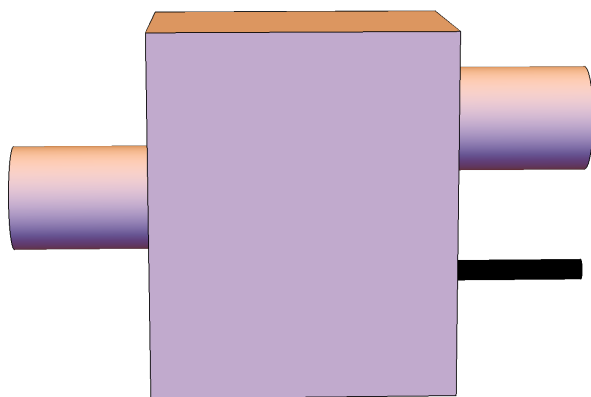
channel  
 $\rightarrow$  *disturbance*



=

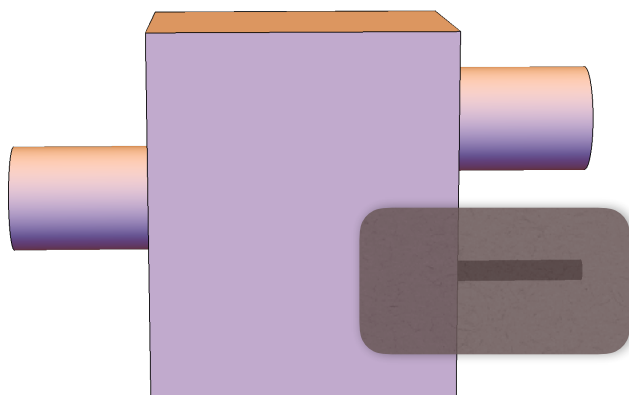


observable/meter  
 $\rightarrow$  *information*

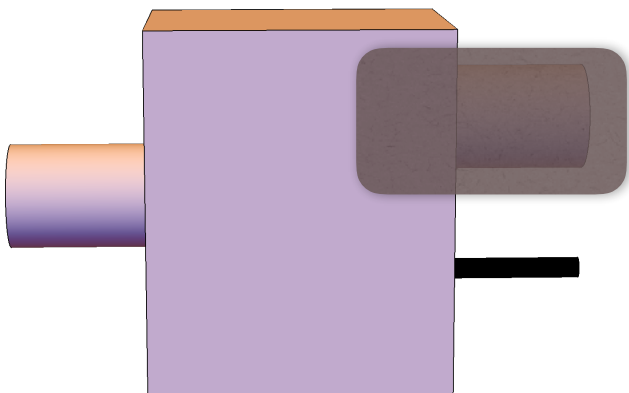


$$I(x, \varrho) = \sum_{y \in \ell_x} K_y \varrho K_y^*$$

$$K_y : \mathcal{H}_{in} \rightarrow \mathcal{H}_{out}$$



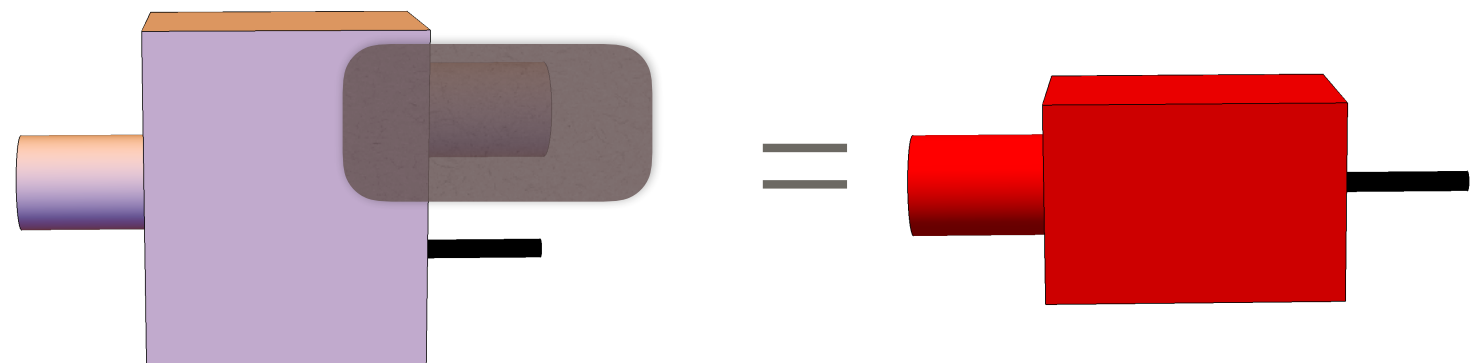
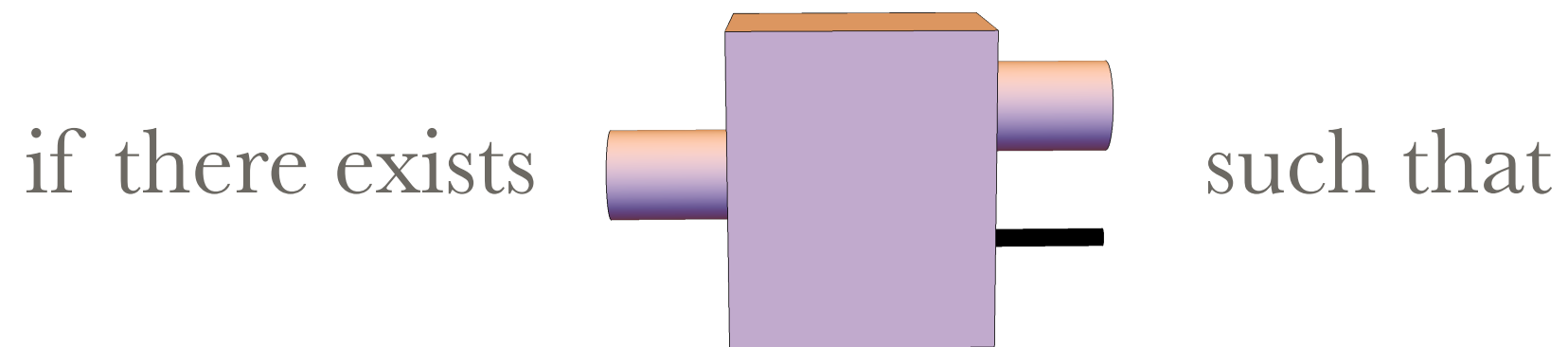
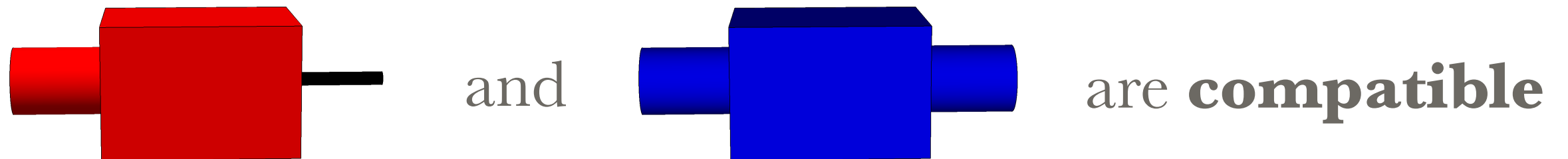
$$\Lambda(\varrho) = \sum_y K_y \varrho K_y^* \quad \text{CPTP map}$$



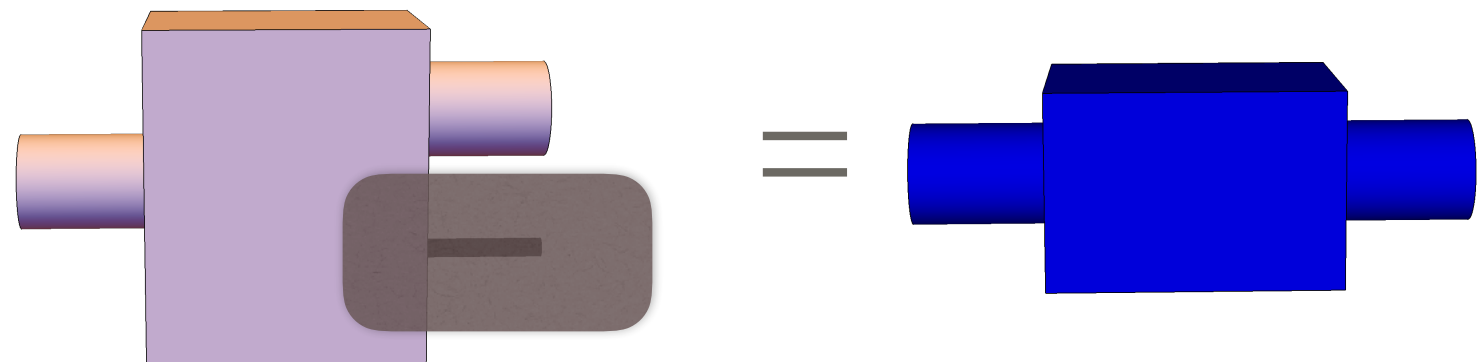
$$A(x) = \sum_{y \in \ell_x} K_y^* K_y \quad \text{POVM}$$



# compatibility relation

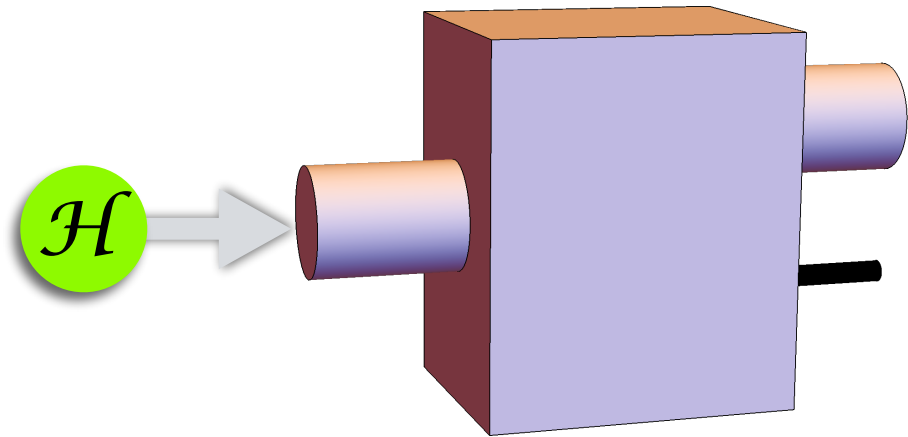


and



# compatibility relation

notation

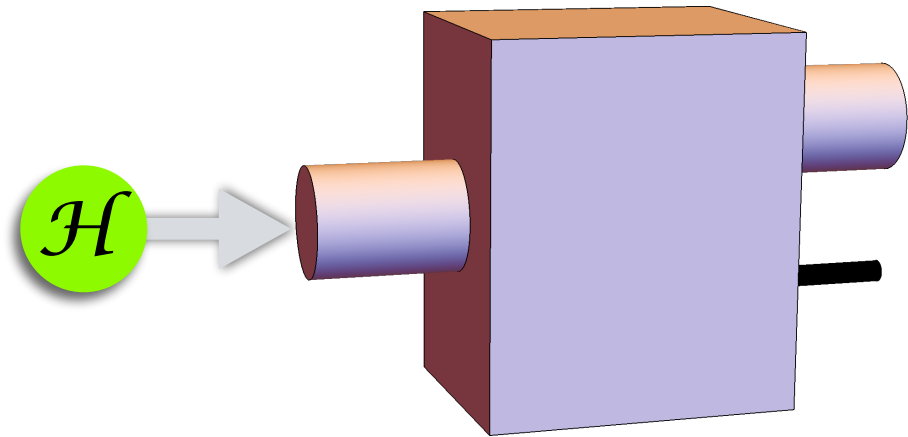


$\mathcal{O}$  = observables with input system  $\mathcal{H}$ , arbitrary output

$\mathcal{C}$  = channels with input system  $\mathcal{H}$ , arbitrary output

# compatibility relation

notation



$\mathcal{O}$  = observables with input system  $\mathcal{H}$ , arbitrary output

$\mathcal{C}$  = channels with input system  $\mathcal{H}$ , arbitrary output

$$\sigma(A) = \{\Lambda \in \mathcal{C} \mid \Lambda \text{ is compatible with } A\}$$

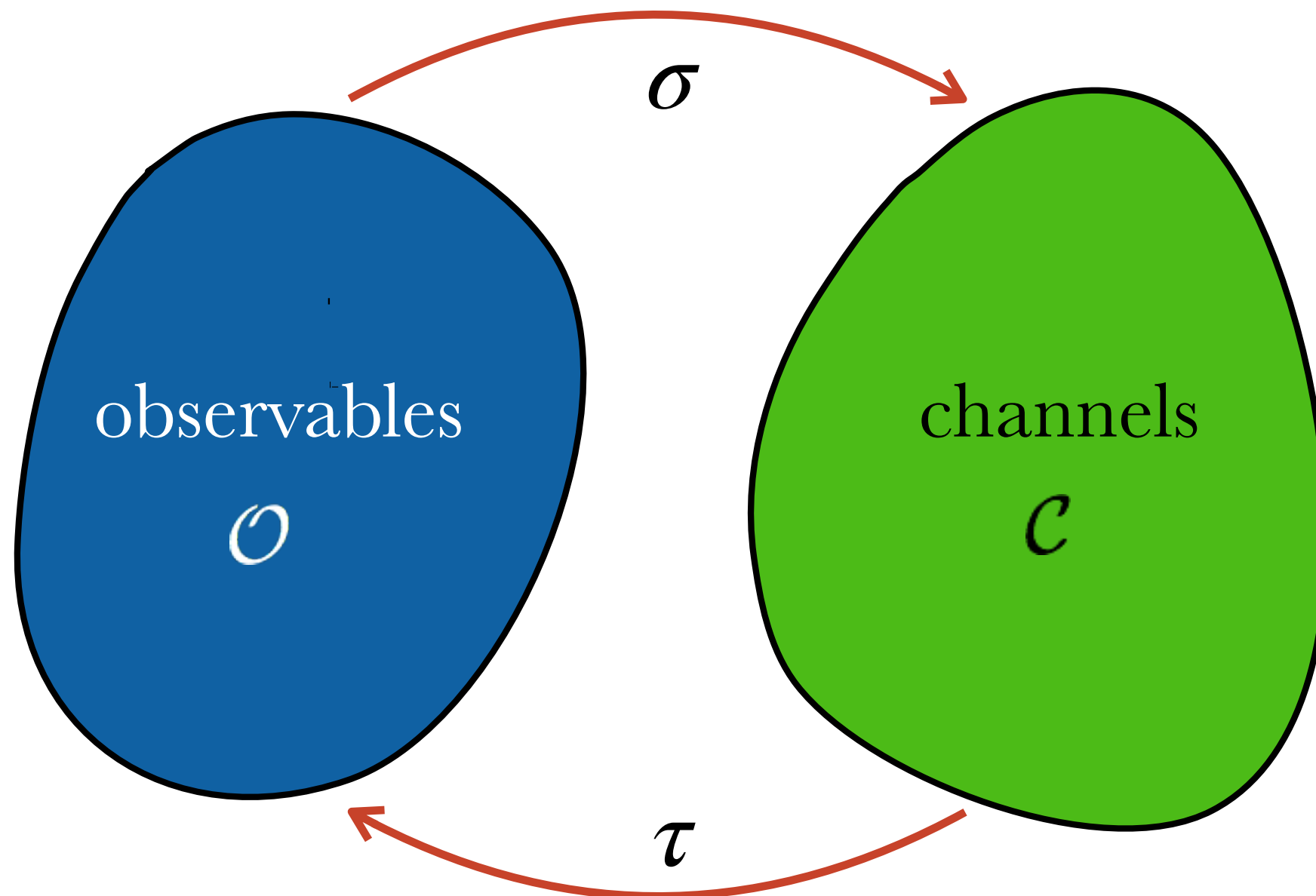
$$\tau(\Lambda) = \{A \in \mathcal{O} \mid A \text{ is compatible with } \Lambda\}$$

# Galois connection

$$\sigma(X) = \bigcap_{A \in X} \sigma(A)$$

$$\tau(Y) = \bigcap_{\Lambda \in Y} \tau(\Lambda)$$

$$\sigma(A) = \{\Lambda \in \mathcal{C} \mid \Lambda \text{ is compatible with } A\} \quad \tau(\Lambda) = \{A \in \mathcal{O} \mid A \text{ is compatible with } \Lambda\}$$



What about noise and disturbance?

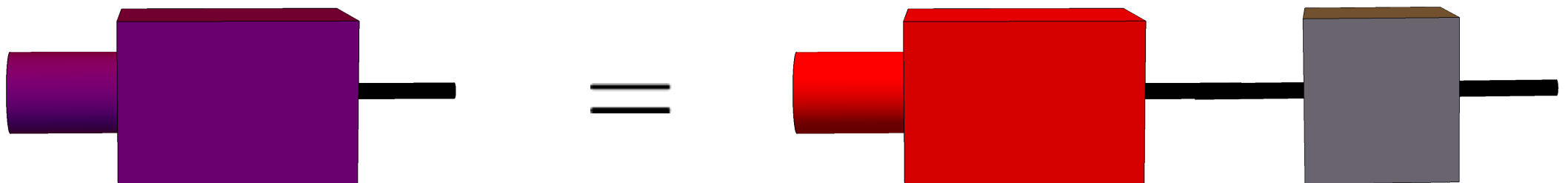


# noise preorder

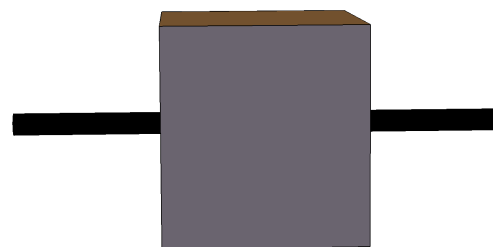
transitive and reflexive relation on the set of observables



if



for some classical channel

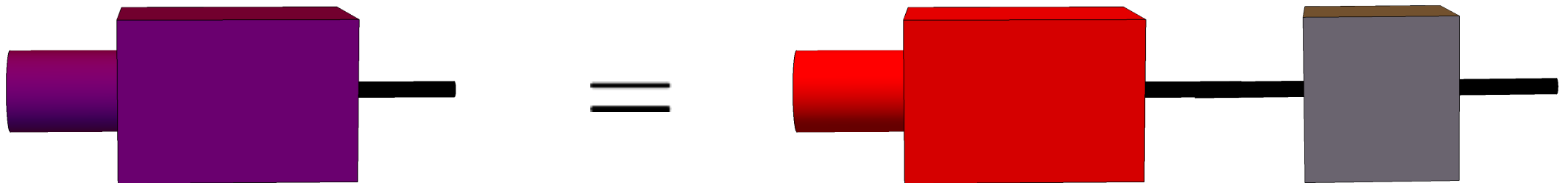


# noise preorder

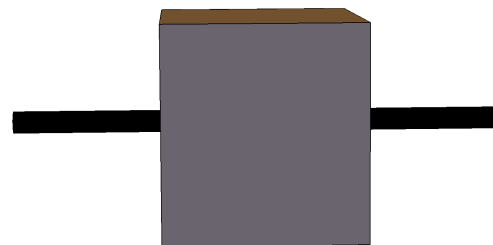
transitive and reflexive relation on the set of observables



if



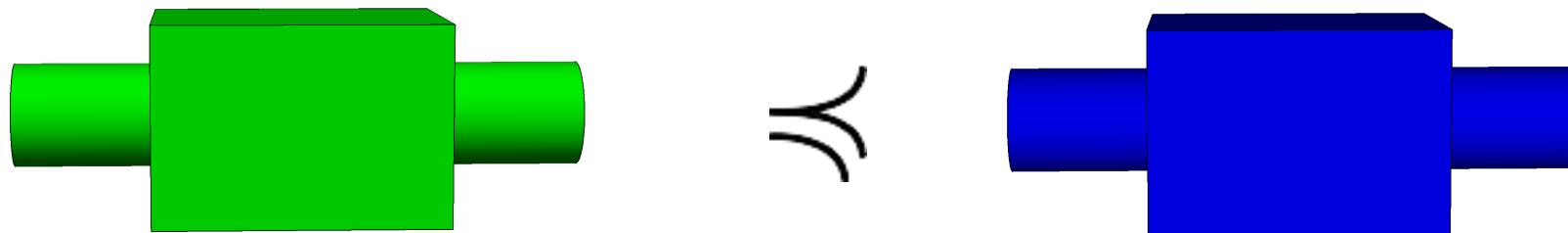
for some classical channel



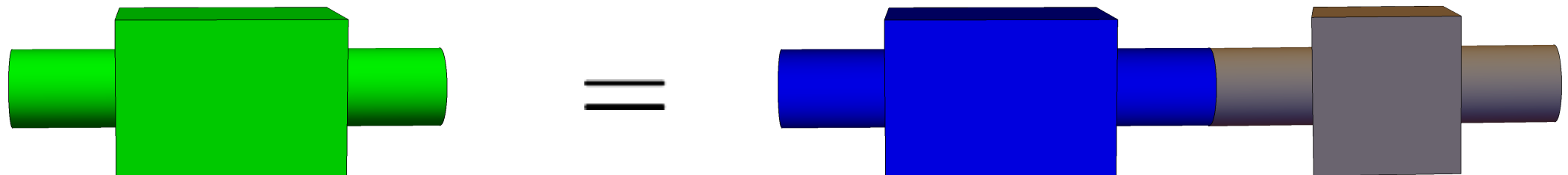
$$\downarrow A = \{B \in O : B \preceq A\}$$

# disturbance preorder

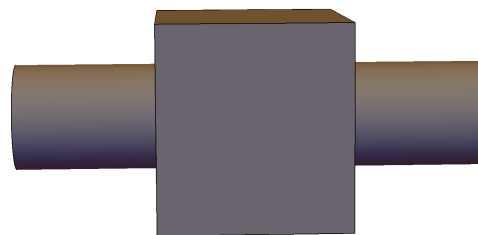
transitive and reflexive relation on the set of channels



if

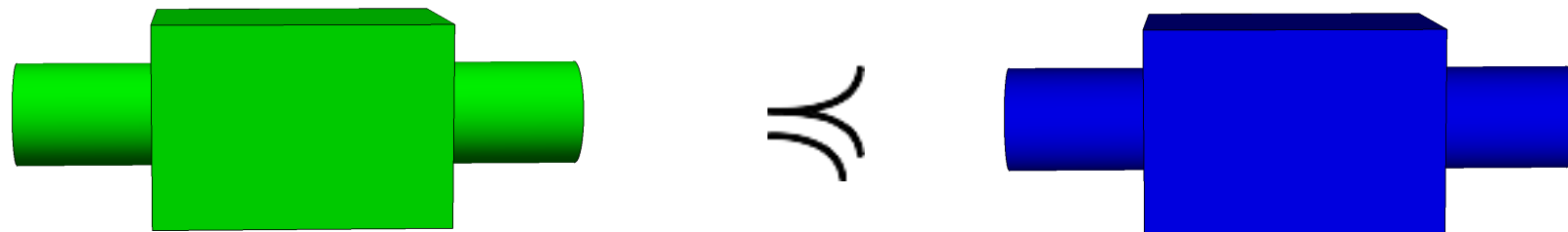


for some quantum channel

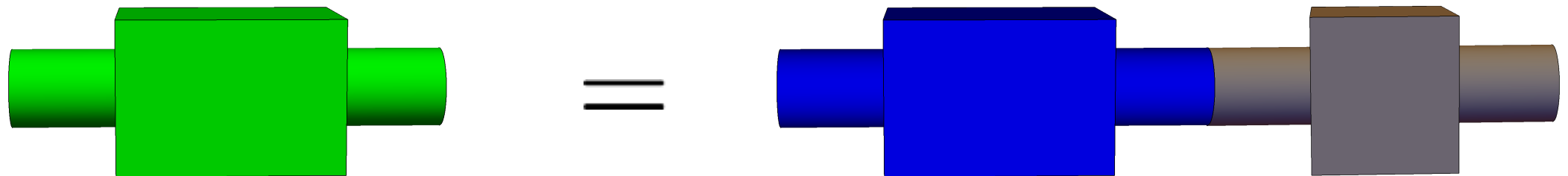


# disturbance preorder

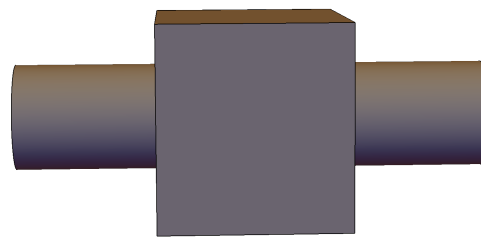
transitive and reflexive relation on the set of channels



if

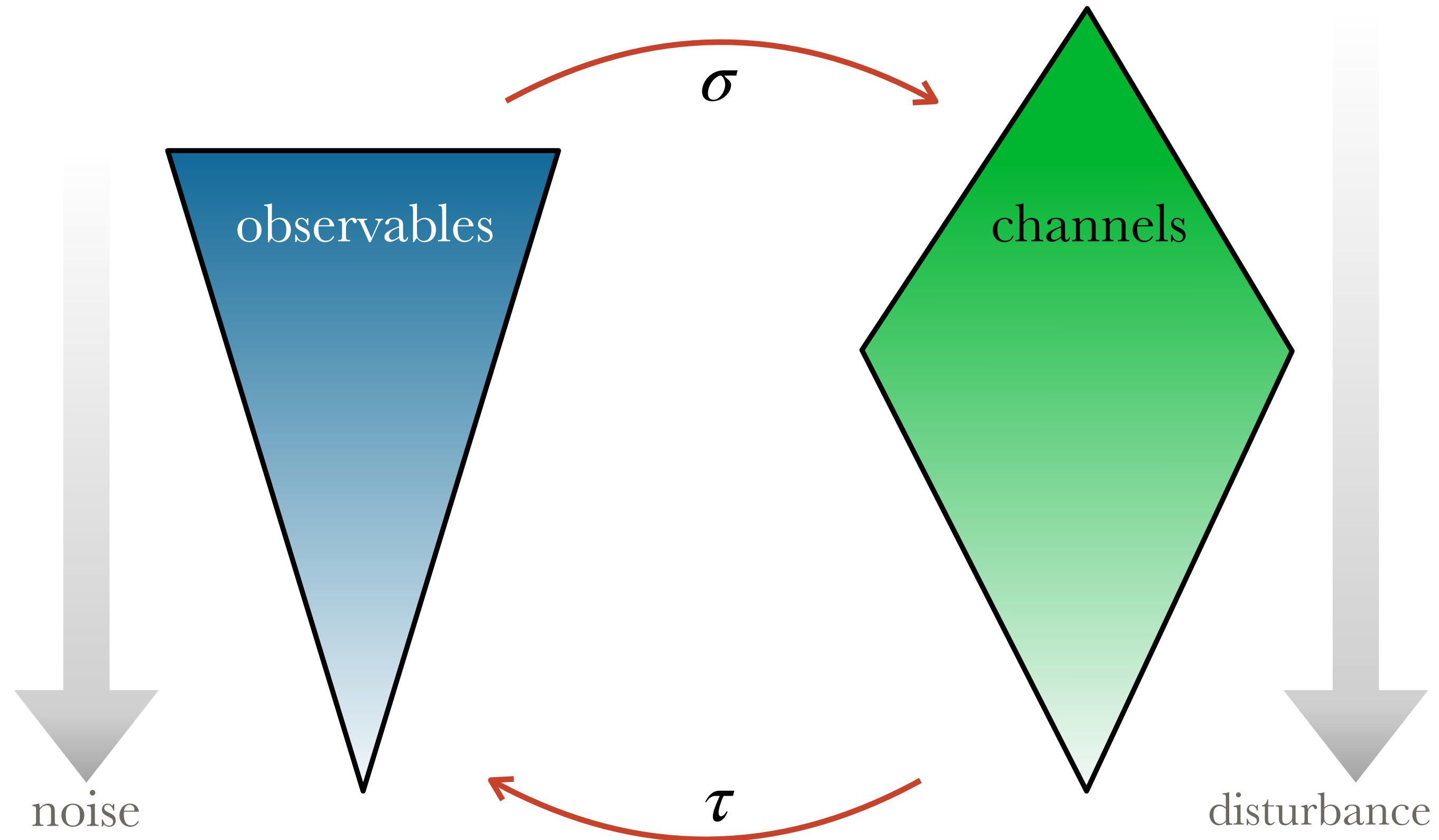


for some quantum channel



$$\downarrow \Lambda = \{\Gamma \in C : \Gamma \preceq \Lambda\}$$

# Galois connection





$$[A] = \{B \in O : A \preceq B \preceq A\}$$



[observables]



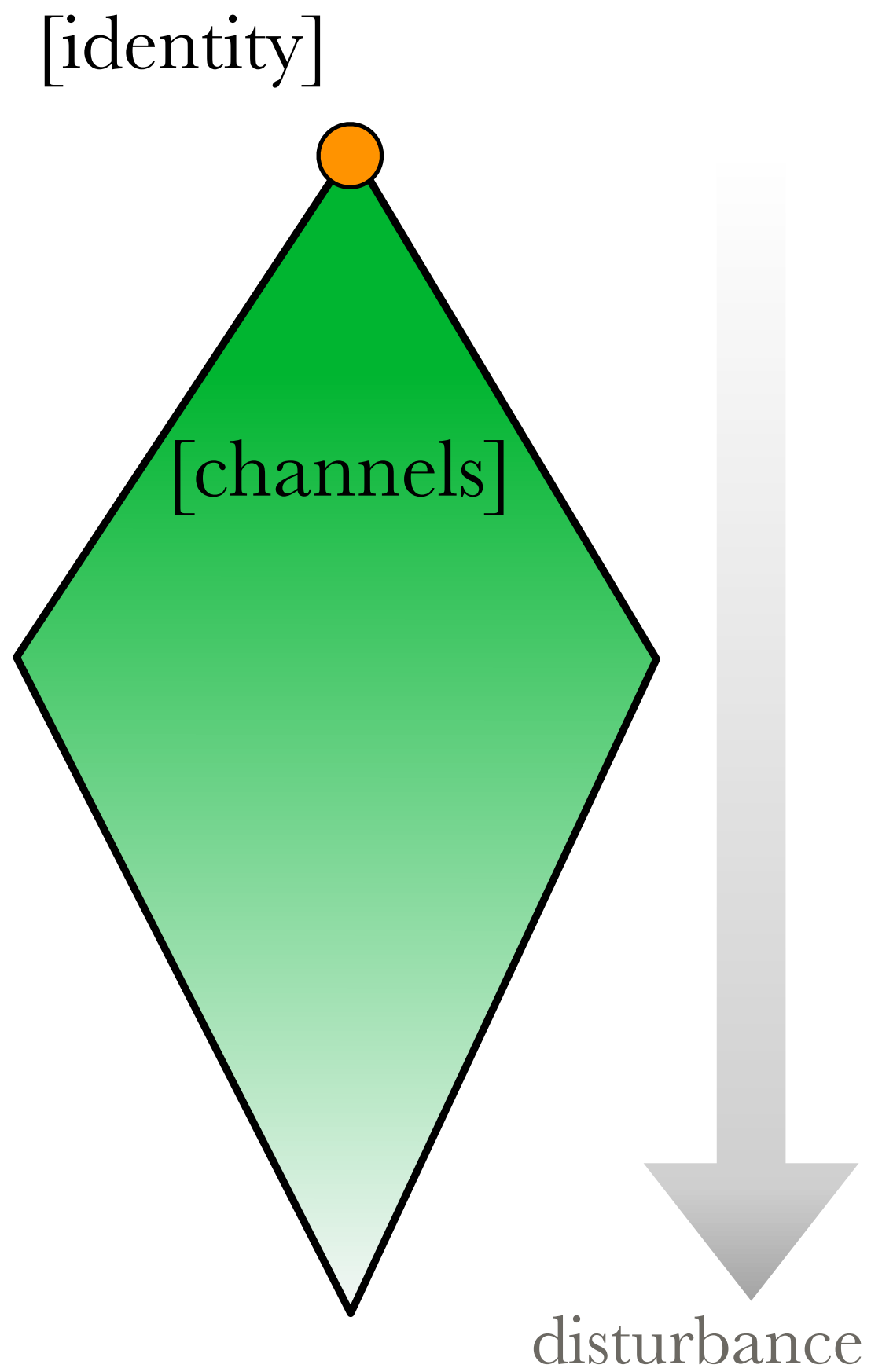
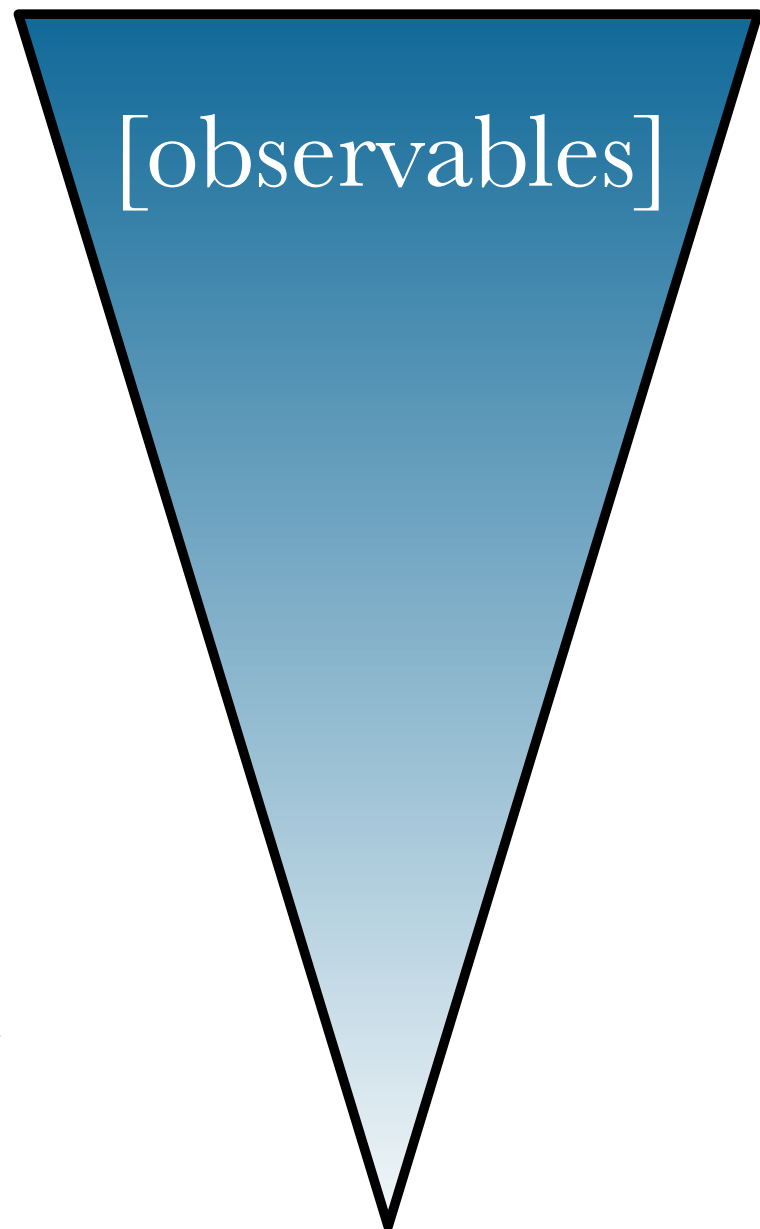
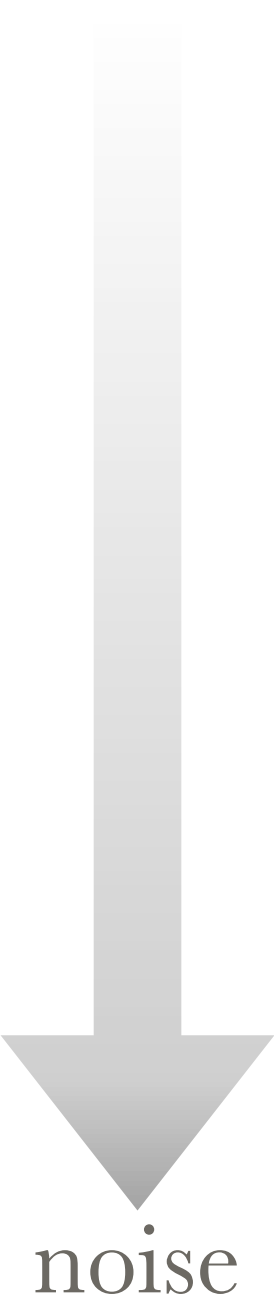
noise

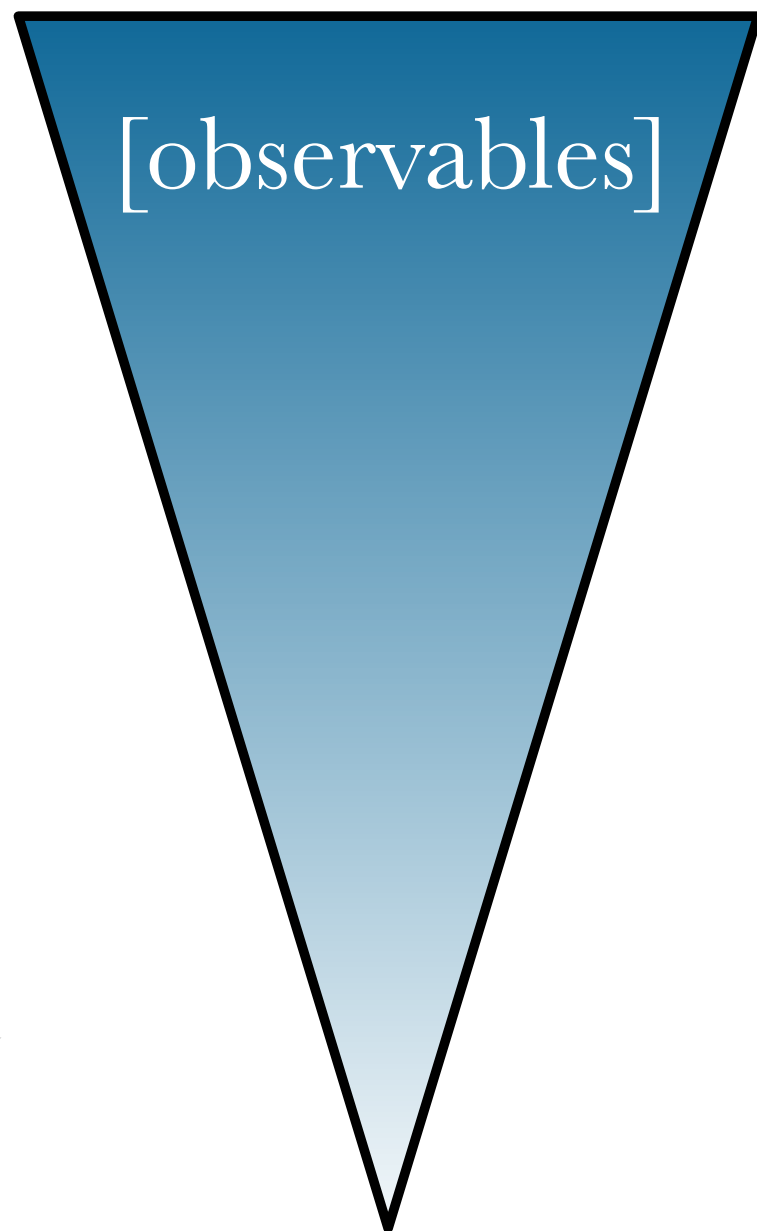
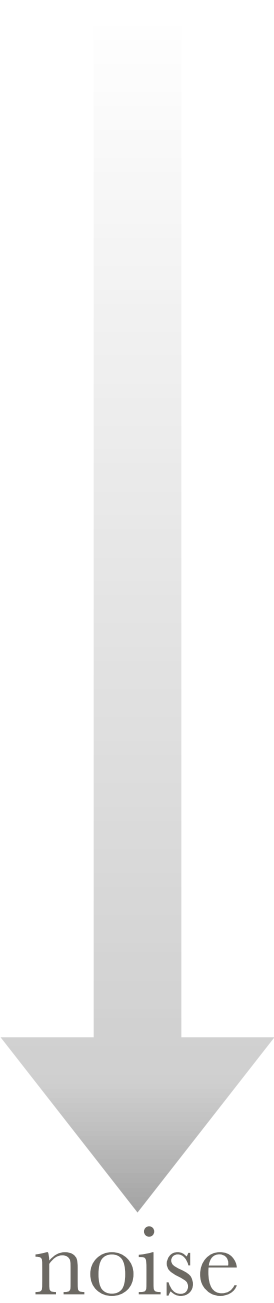


[channels]

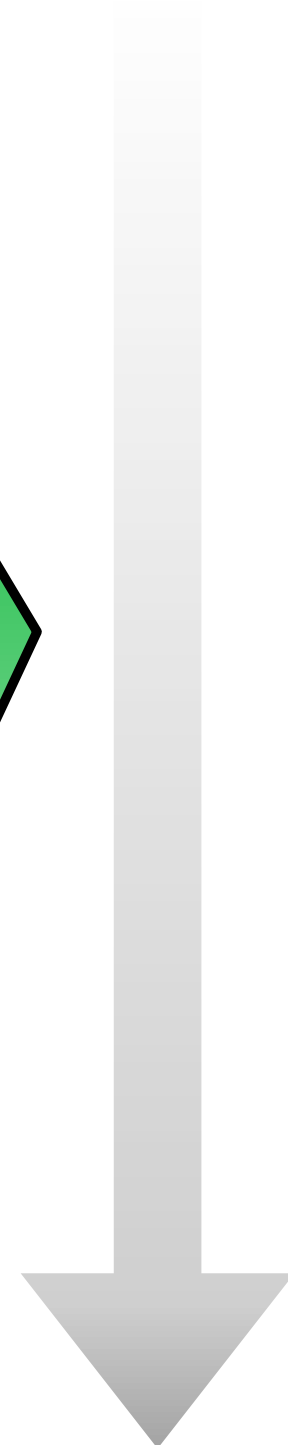
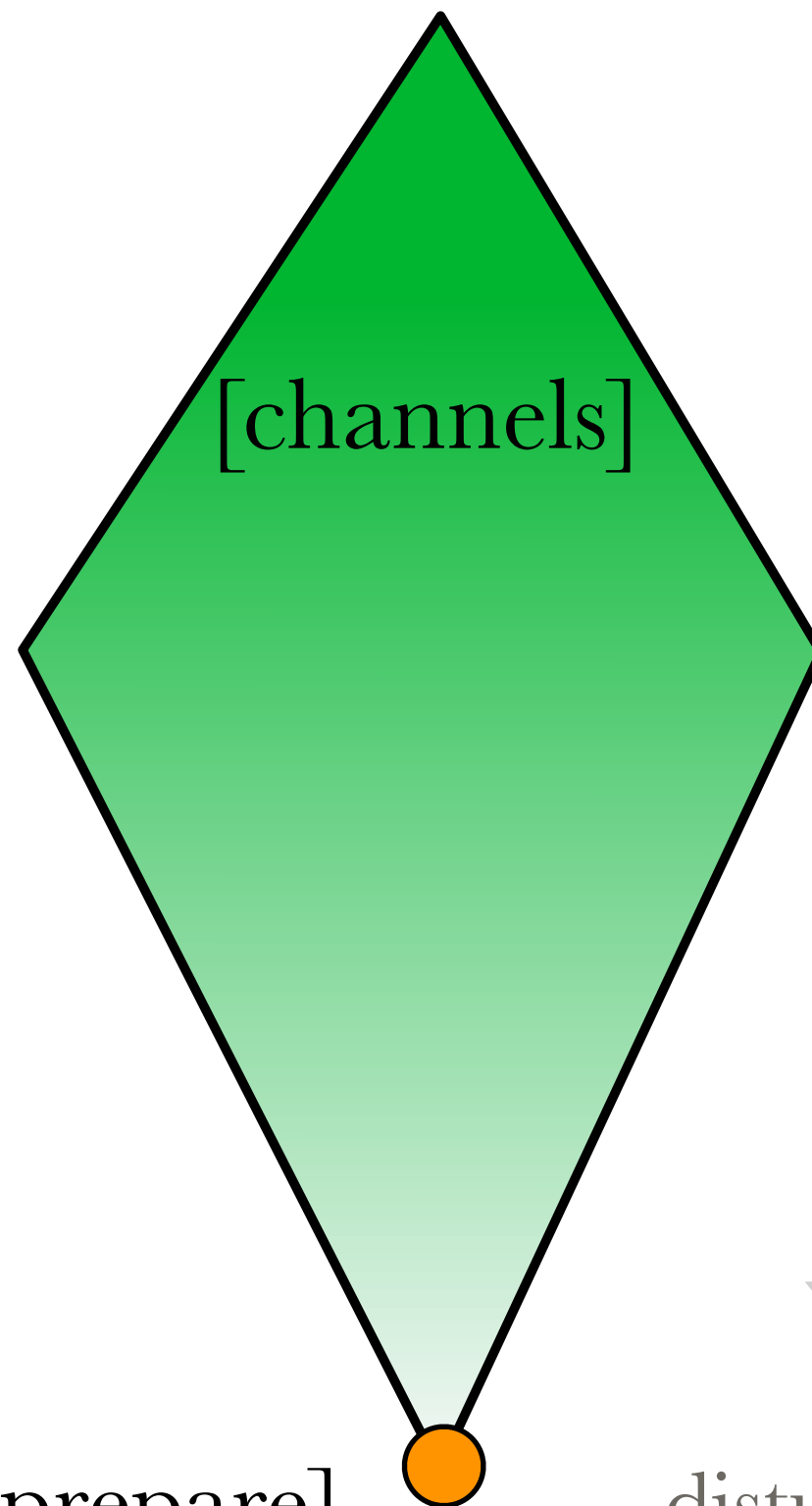


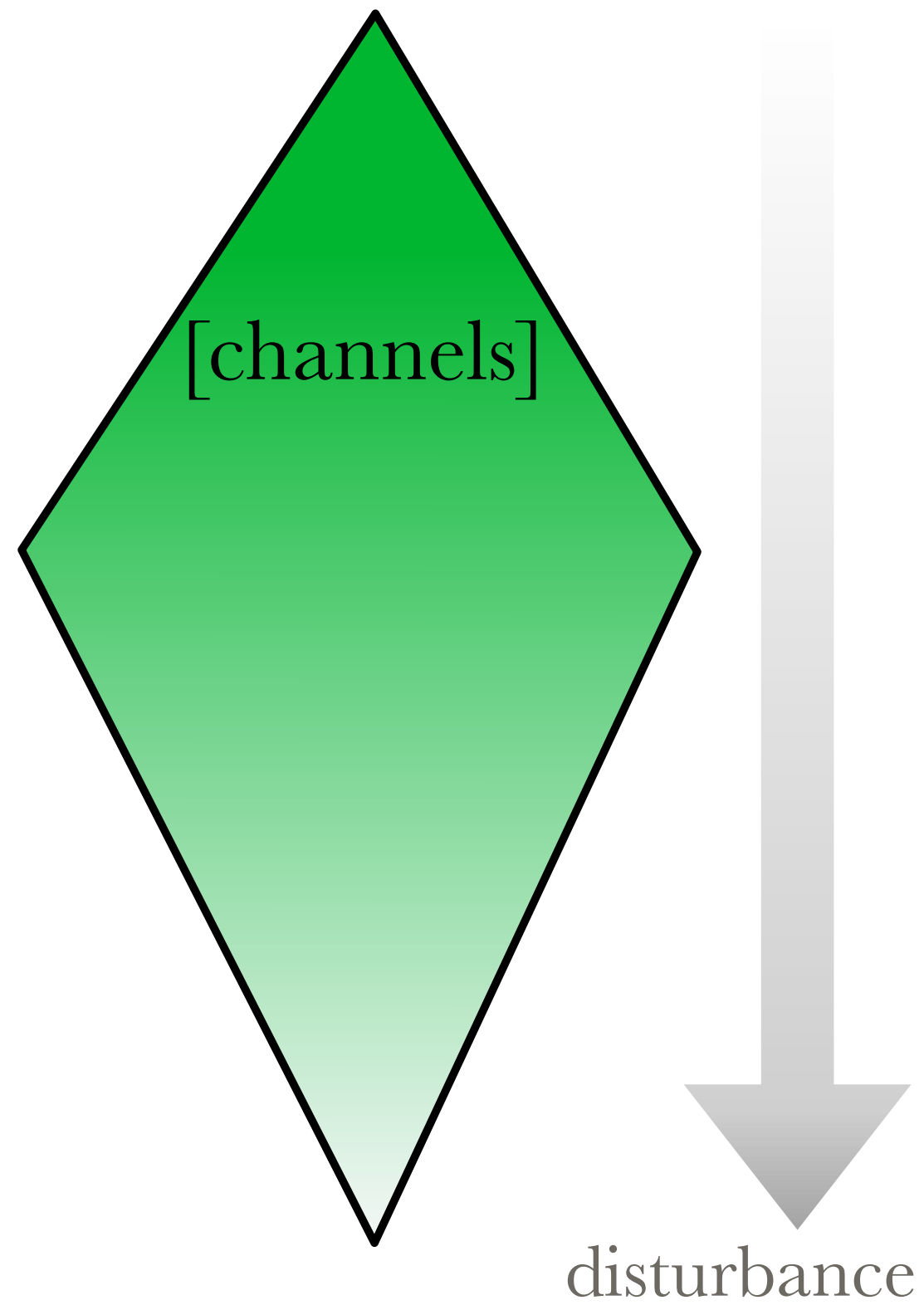
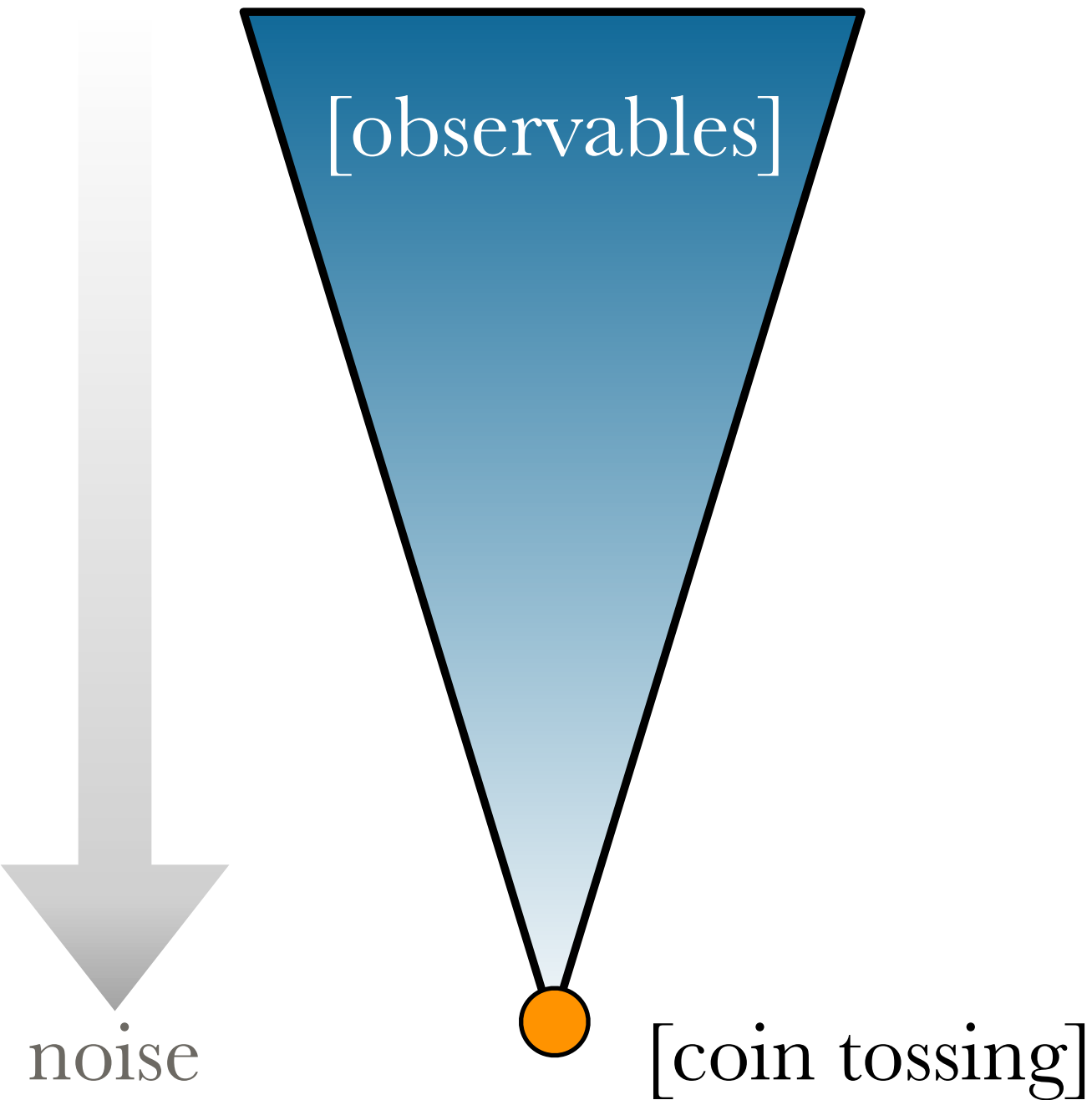
disturbance



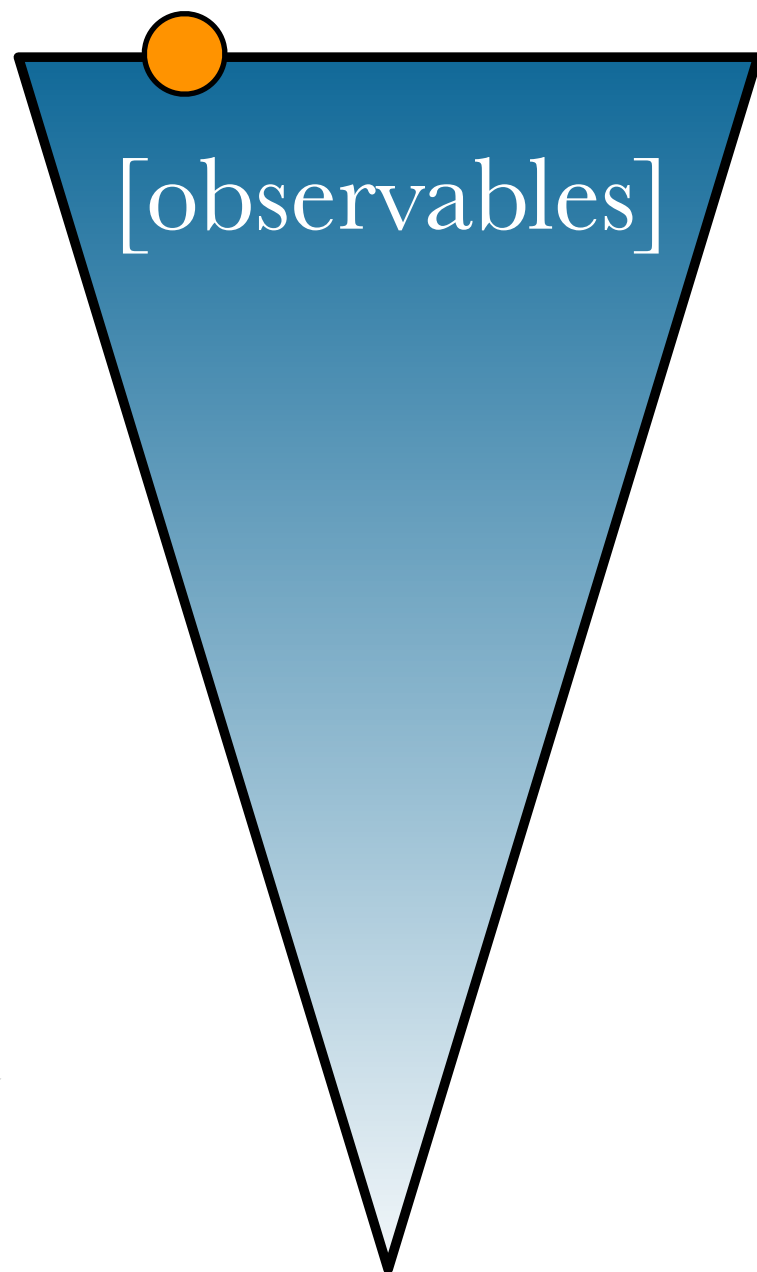


[discard-prepare]

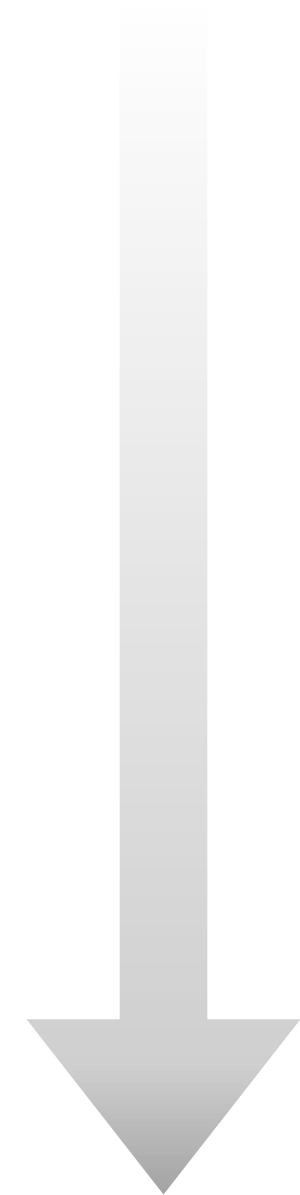




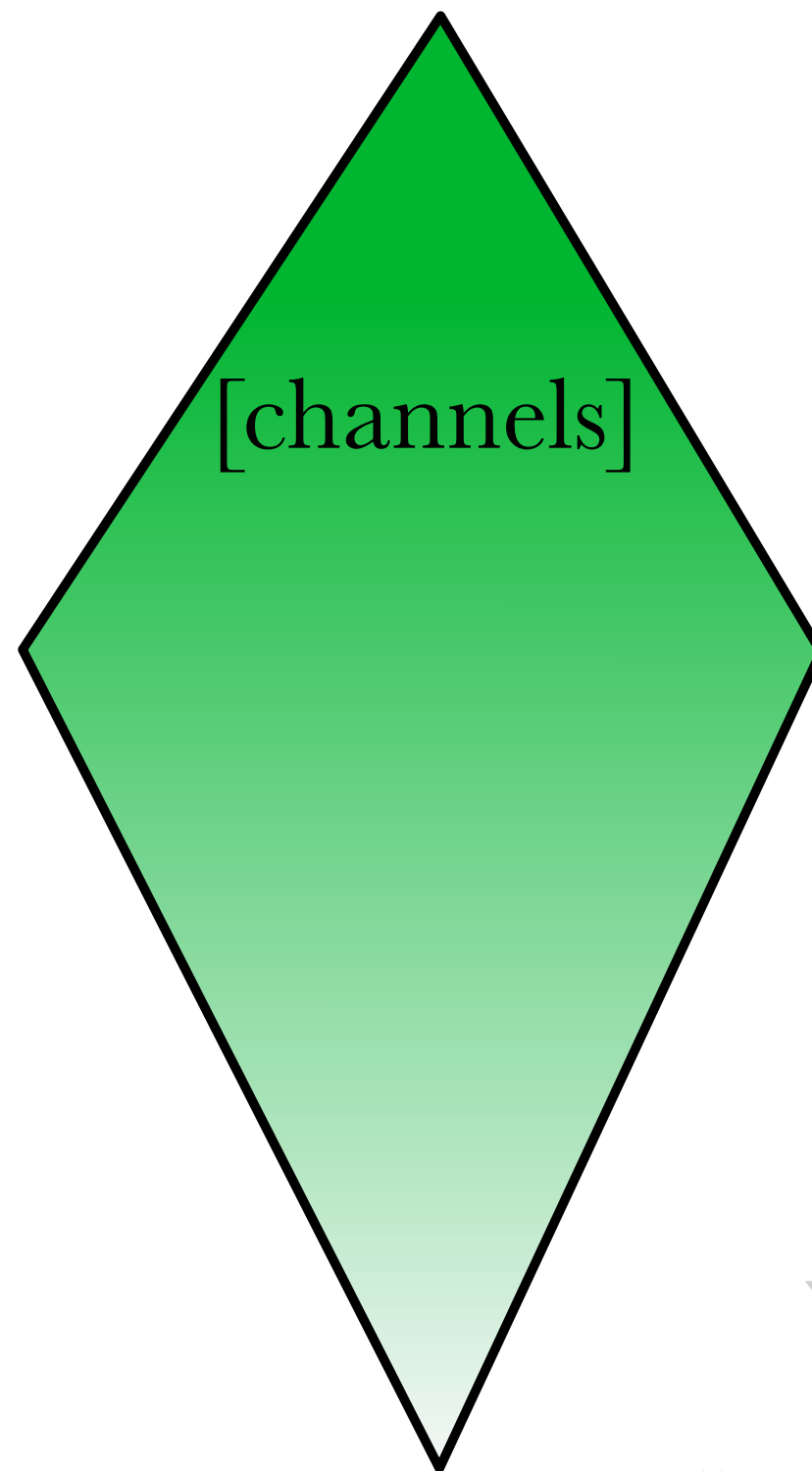
[rank-1 POVM]



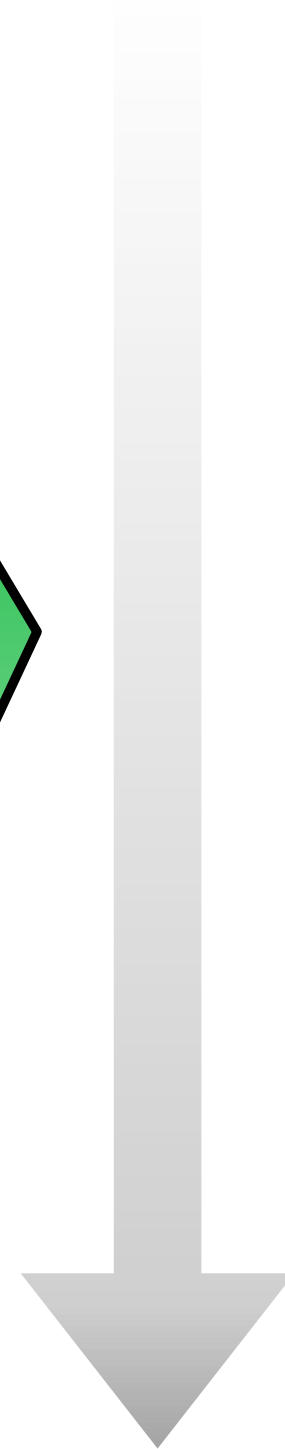
[observables]



noise

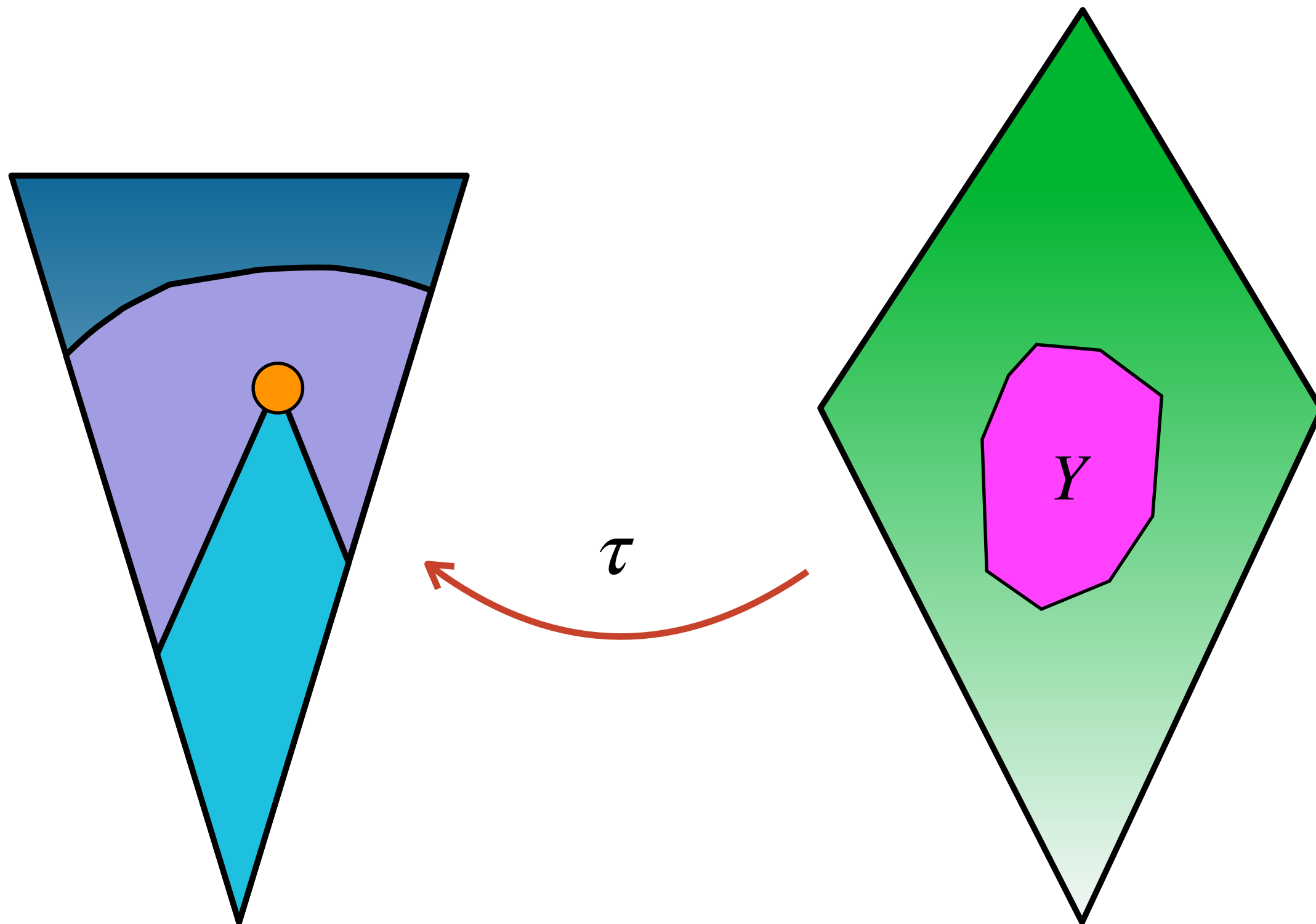


[channels]



disturbance

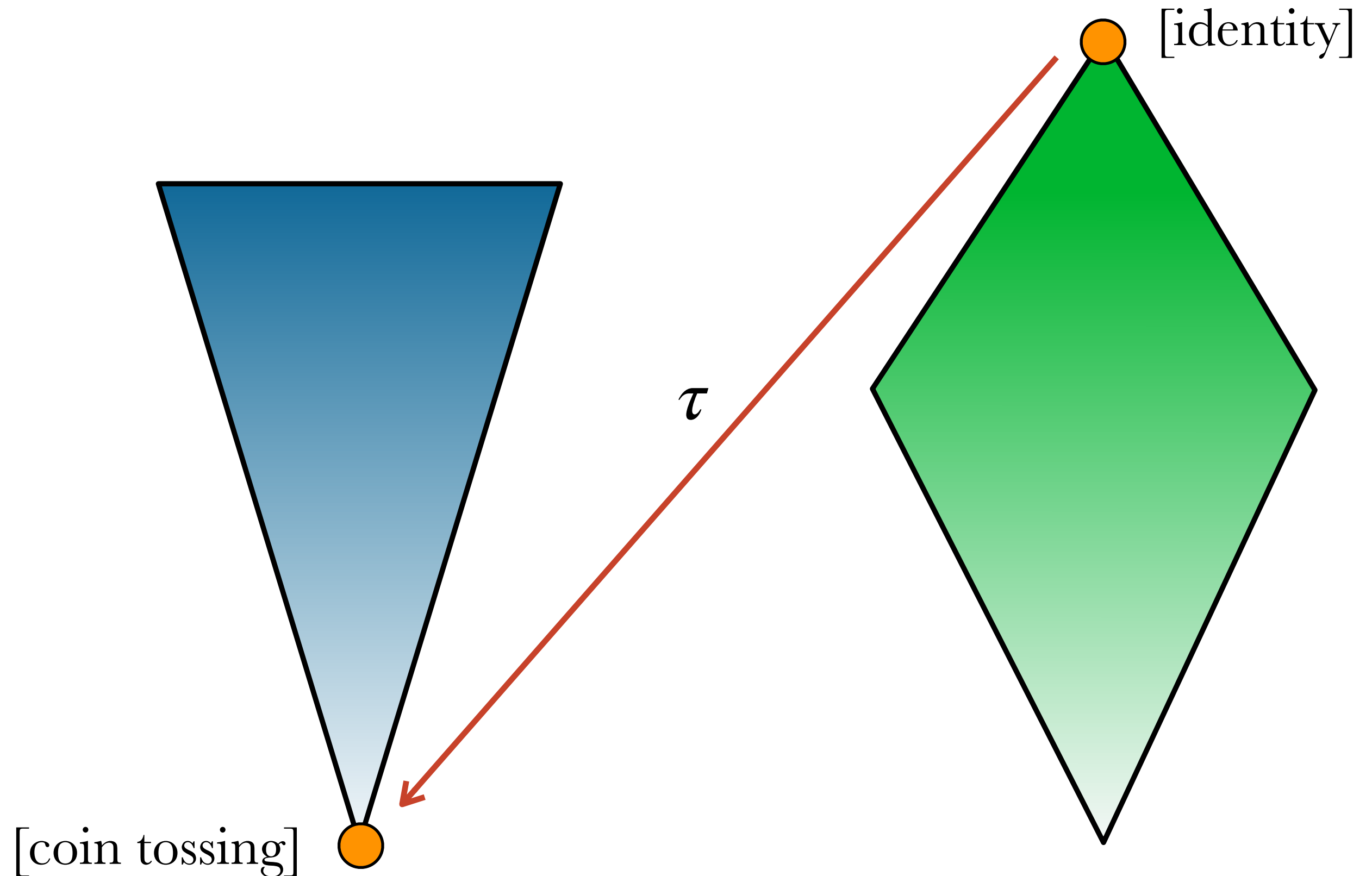
$$A \in \tau(Y) \implies \downarrow A \subseteq \tau(Y)$$



$$A \in \tau(Y) \implies \downarrow A \subseteq \tau(Y)$$

$$\Lambda \in \sigma(X) \implies \downarrow \Lambda \subseteq \sigma(X)$$

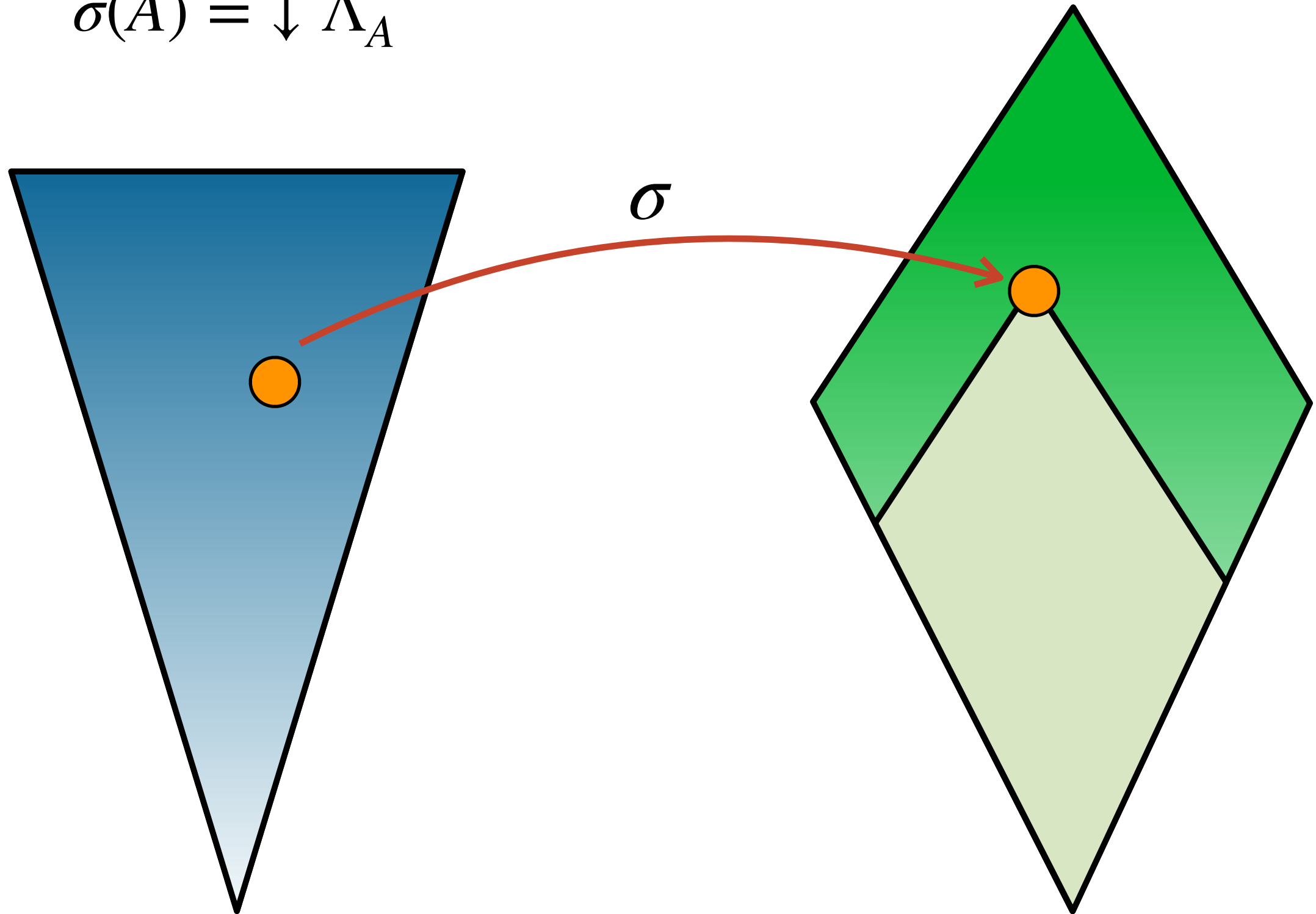
# A) no-information-without-disturbance





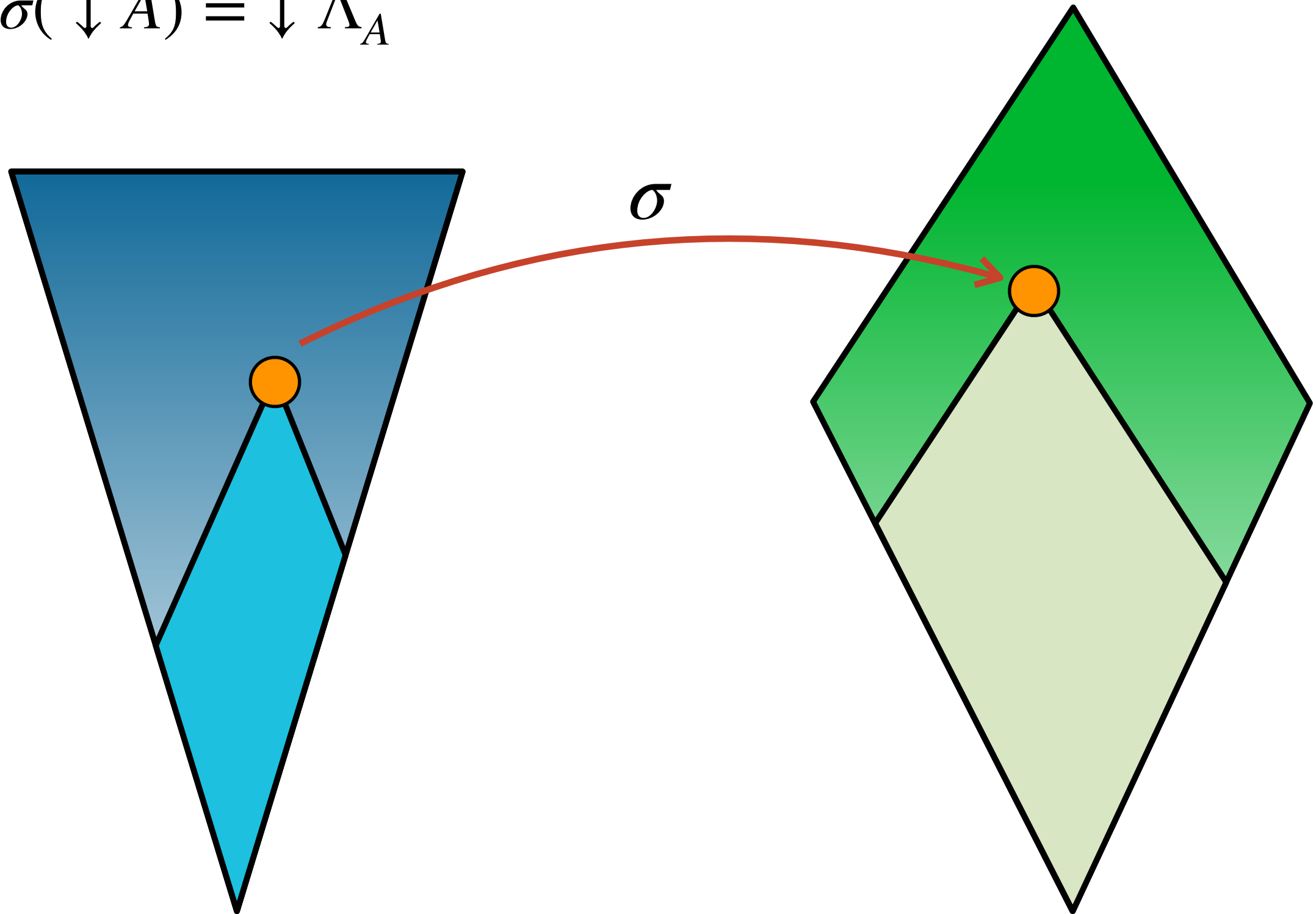
## B) existence of a least disturbing channel

$$\sigma(A) = \downarrow \Lambda_A$$



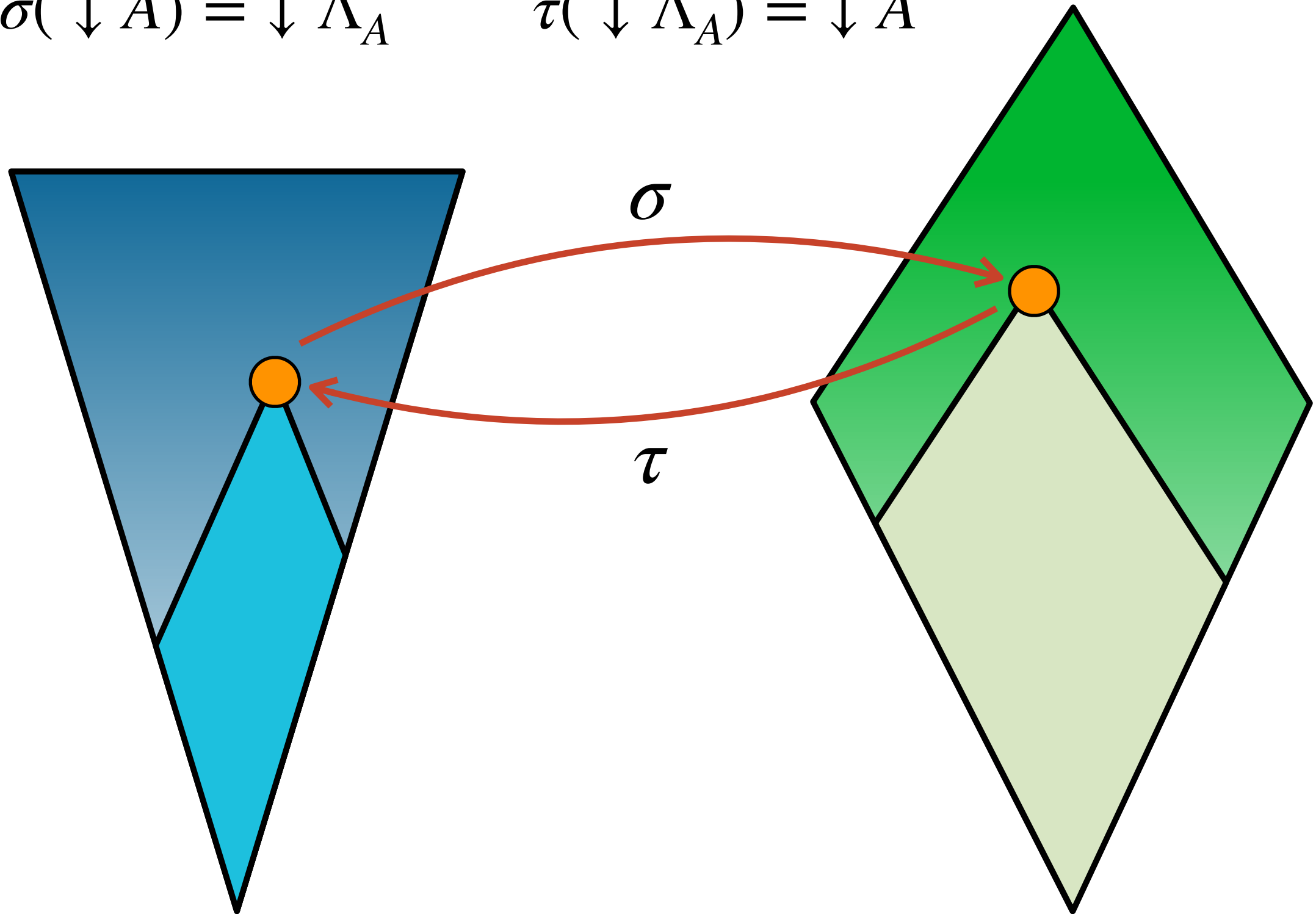
## B) existence of a least disturbing channel

$$\sigma(\downarrow A) = \downarrow \Lambda_A$$



## B) existence of a least disturbing channel

$$\sigma(\downarrow A) = \downarrow \Lambda_A \quad \tau(\downarrow \Lambda_A) = \downarrow A$$



## B) existence of a least disturbing channel

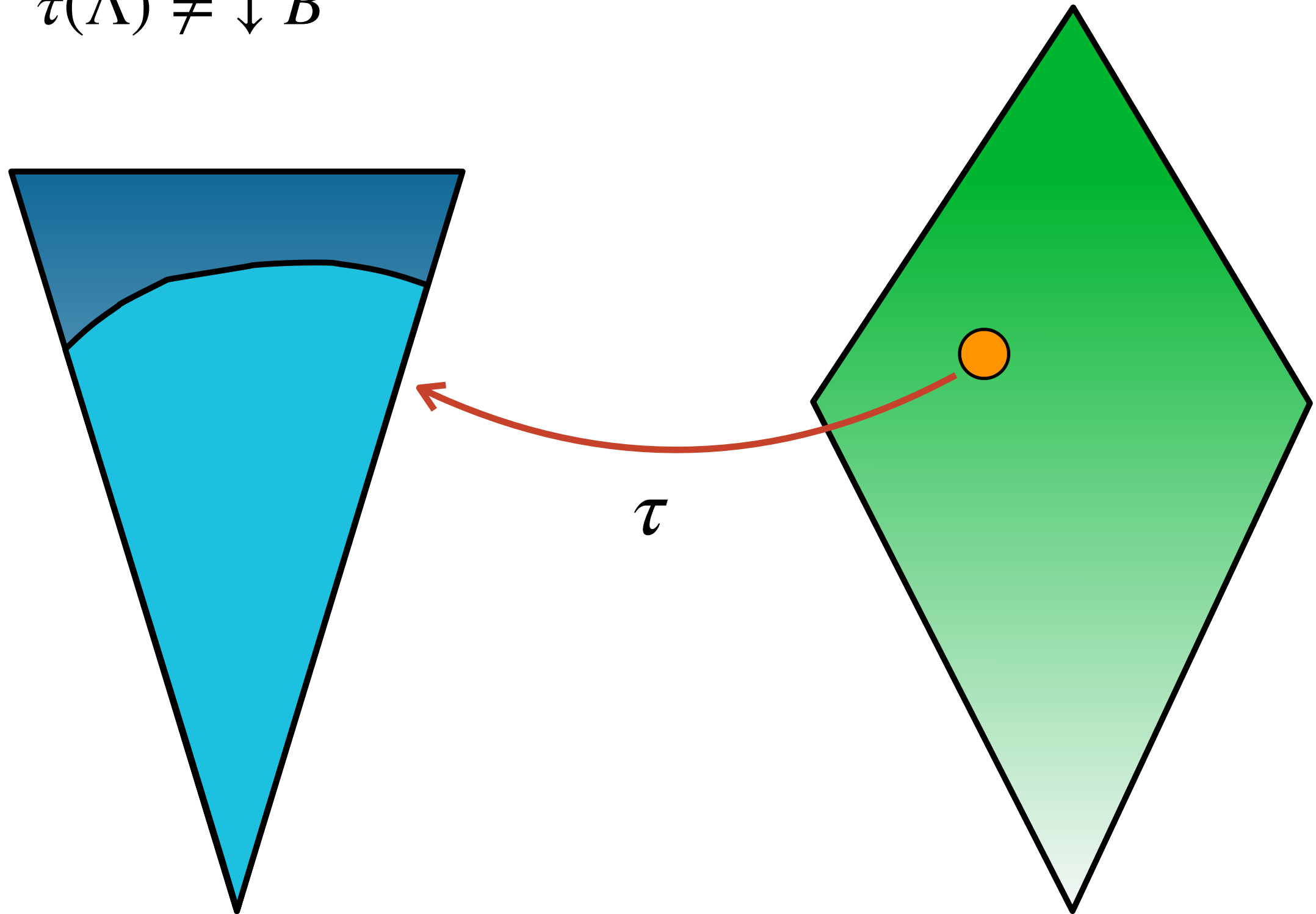
$$\sigma(\downarrow A) = \downarrow \Lambda_A \qquad \tau(\downarrow \Lambda_A) = \downarrow A$$

Naimark dilation:  $V^* \hat{A}(x) V = A(x)$

$$\Lambda_A(\varrho) = \sum_x \hat{A}(x) V \varrho V^* \hat{A}(x)$$

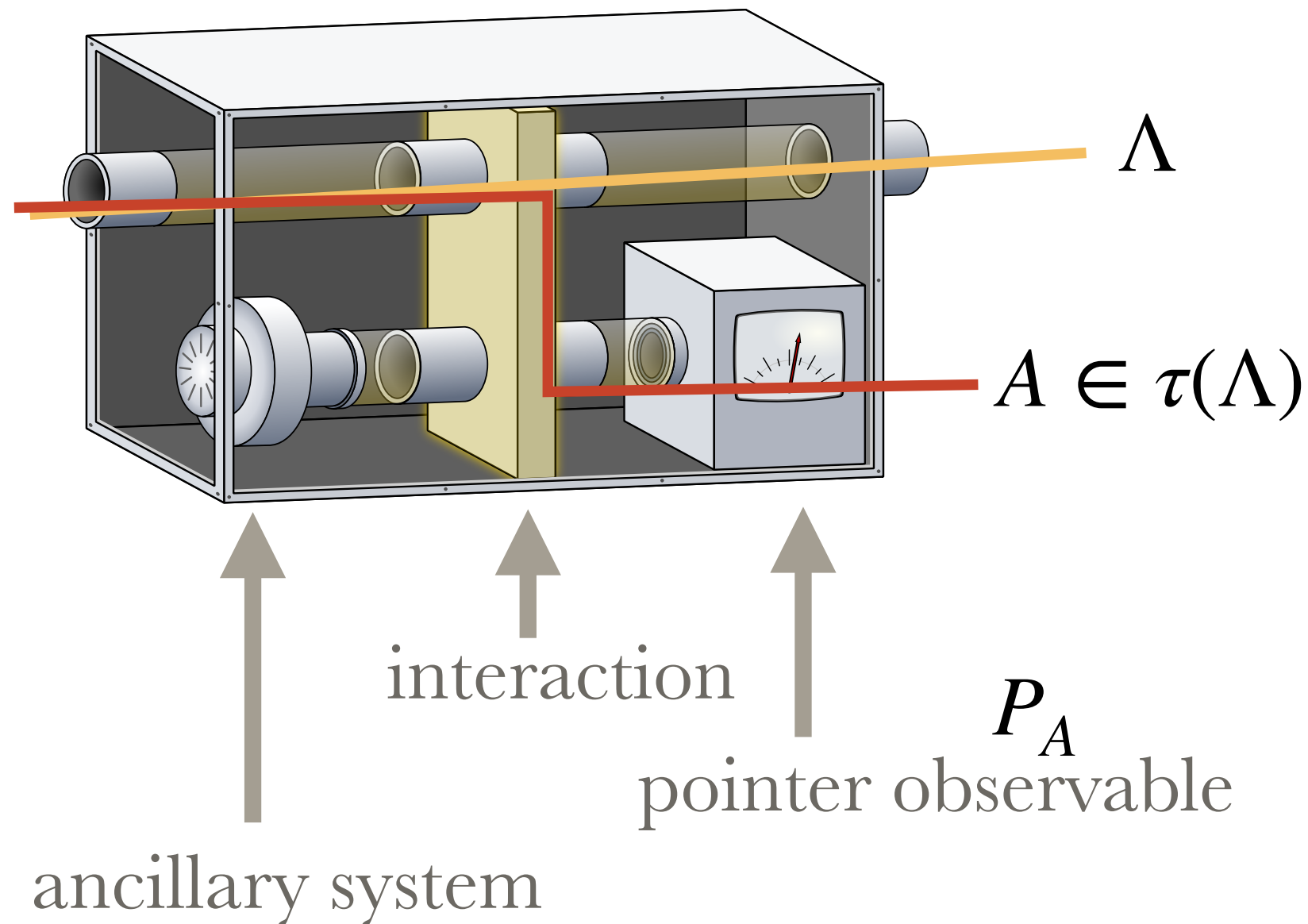
# C) non-existence of a least noisy observable

$$\tau(\Lambda) \neq \downarrow B$$



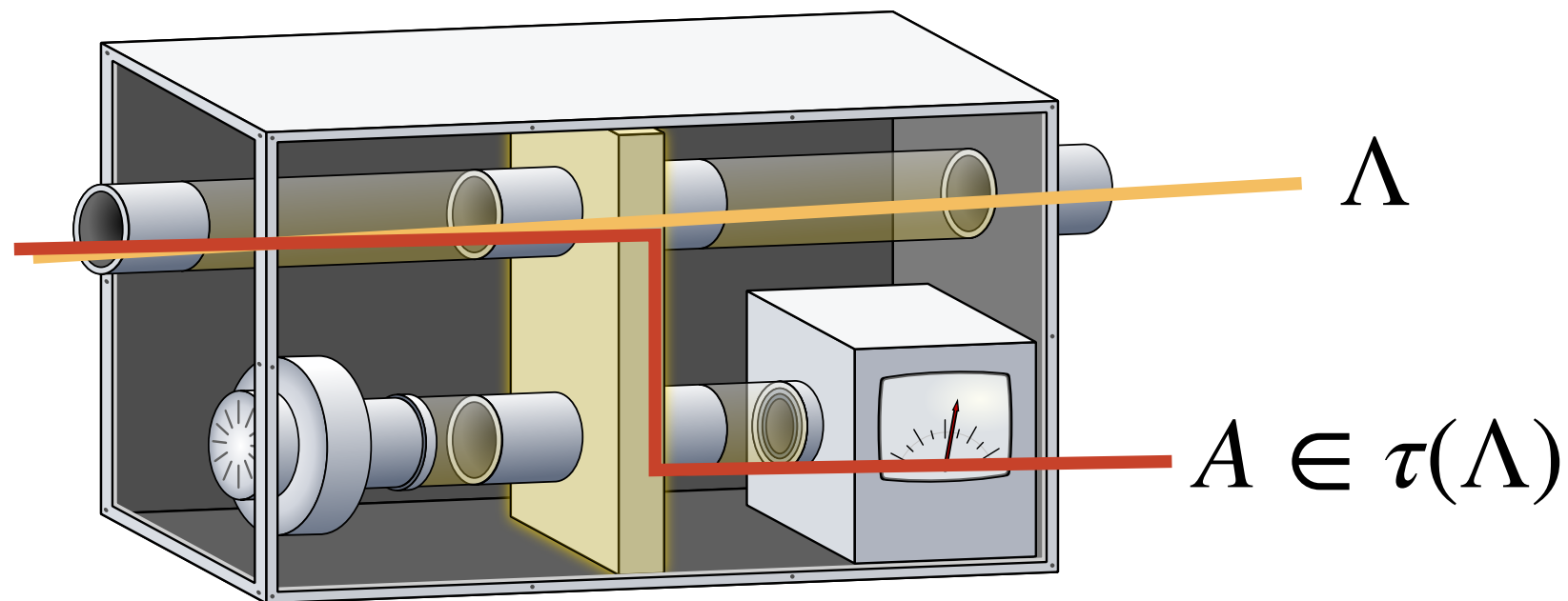
# C) non-existence of a least noisy observable

$\tau(\Lambda)$  : fix a realization for  $\Lambda$  and go through all pointer observables



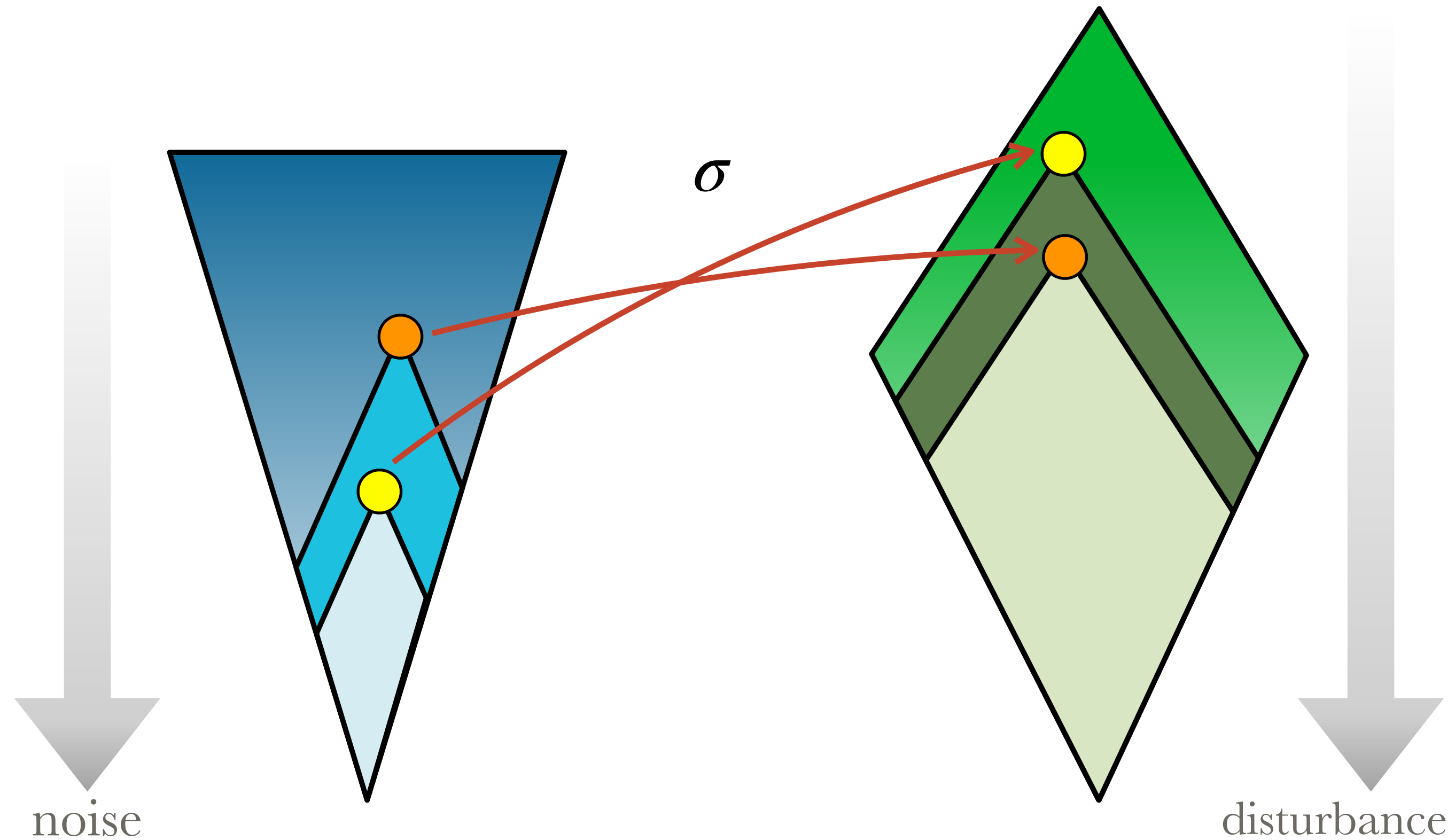
## C) non-existence of a least noisy observable

$\tau(\Lambda)$  : fix a realization for  $\Lambda$  and go through all pointer observables



$$\text{tr}[\varrho A(x)] = \text{tr}[U \varrho \otimes \xi U^* I \otimes P_A(x)]$$

# D) qualitative noise-disturbance relation





D) qualitative noise-disturbance relation

$$A \preceq B \quad \Longleftrightarrow \quad \sigma(A) \supseteq \sigma(B)$$

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Holds also in other operational theories than quantum:

$$A \preceq B \quad \Rightarrow \quad \sigma(A) \supseteq \sigma(B)$$

## D) qualitative noise-disturbance relation

$$A \preceq B \quad \Longleftrightarrow \quad \sigma(A) \supseteq \sigma(B)$$

Holds also in other operational theories than quantum:

$$A \preceq B \quad \Rightarrow \quad \sigma(A) \supseteq \sigma(B)$$

Does **not** hold in all operational theories:

$$A \preceq B \quad \Leftarrow \quad \sigma(A) \supseteq \sigma(B)$$

# quantifications of noise and disturbance

## Basic requirements

$$A \preceq B \implies \textit{noise}(A) \leq \textit{noise}(B)$$

$$\Lambda \preceq \Gamma \implies \textit{disturbance}(\Lambda) \leq \textit{disturbance}(\Gamma)$$

# quantifications of noise and disturbance

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PRL **112**, 050401 (2014)

PHYSICAL REVIEW LETTERS

week ending  
7 FEBRUARY 2014

## Noise and Disturbance in Quantum Measurements: An Information-Theoretic Approach

Francesco Buscemi,<sup>1,\*</sup> Michael J. W. Hall,<sup>2,†</sup> Masanao Ozawa,<sup>3,‡</sup> and Mark M. Wilde<sup>4,§</sup>

**Theorem 1:** For any measuring apparatus  $\mathcal{M}$  and any nondegenerate observables  $X$  and  $Z$ , the following tradeoff between noise  $N(\mathcal{M}, X)$  and disturbance  $D(\mathcal{M}, Z)$  holds:

$$N(\mathcal{M}, X) + D(\mathcal{M}, Z) \geq -\log c, \quad (1)$$

where  $c := \max_{x,z} |\langle \psi^x | \varphi^z \rangle|^2$  and the log is in base 2.

# closure maps

$c : 2^{\mathcal{A}} \rightarrow 2^{\mathcal{A}}$  is a closure map if

- ①  $c \circ c = c$
- ②  $X \subseteq c(X)$
- ③  $X' \subseteq X \Rightarrow c(X') \subseteq c(X)$

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- ③  $X' \subseteq X \Rightarrow c(X') \subseteq c(X)$

---

Examples:

- topological closure
- linear span
- convex hull

# closure maps

$c : 2^{\mathcal{A}} \rightarrow 2^{\mathcal{A}}$  is a closure map if

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In a Galois connection  $\tau\sigma$  and  $\sigma\tau$  are closure maps.

Further,  $\tau\sigma\tau = \tau$  and  $\sigma\tau\sigma = \sigma$ .



# closure maps

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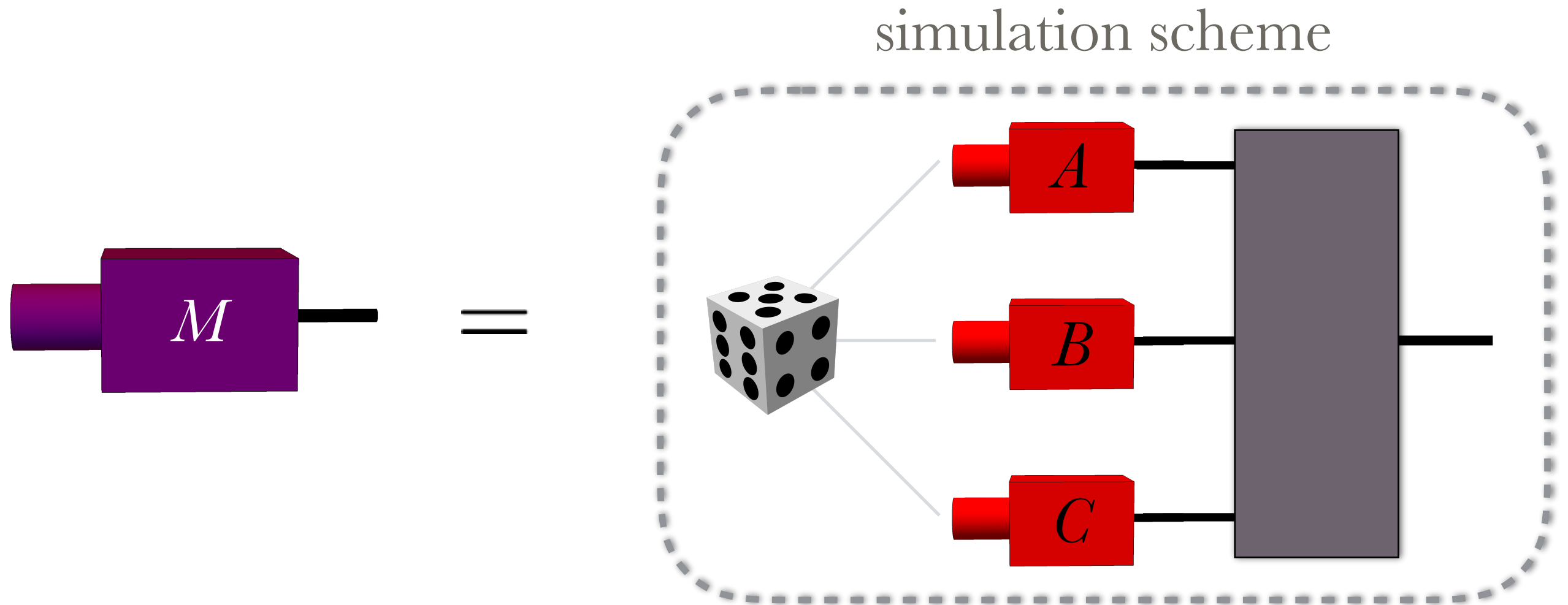
- ①  $c \circ c = c$
- ②  $X \subseteq c(X)$
- ③  $X' \subseteq X \Rightarrow c(X') \subseteq c(X)$

---

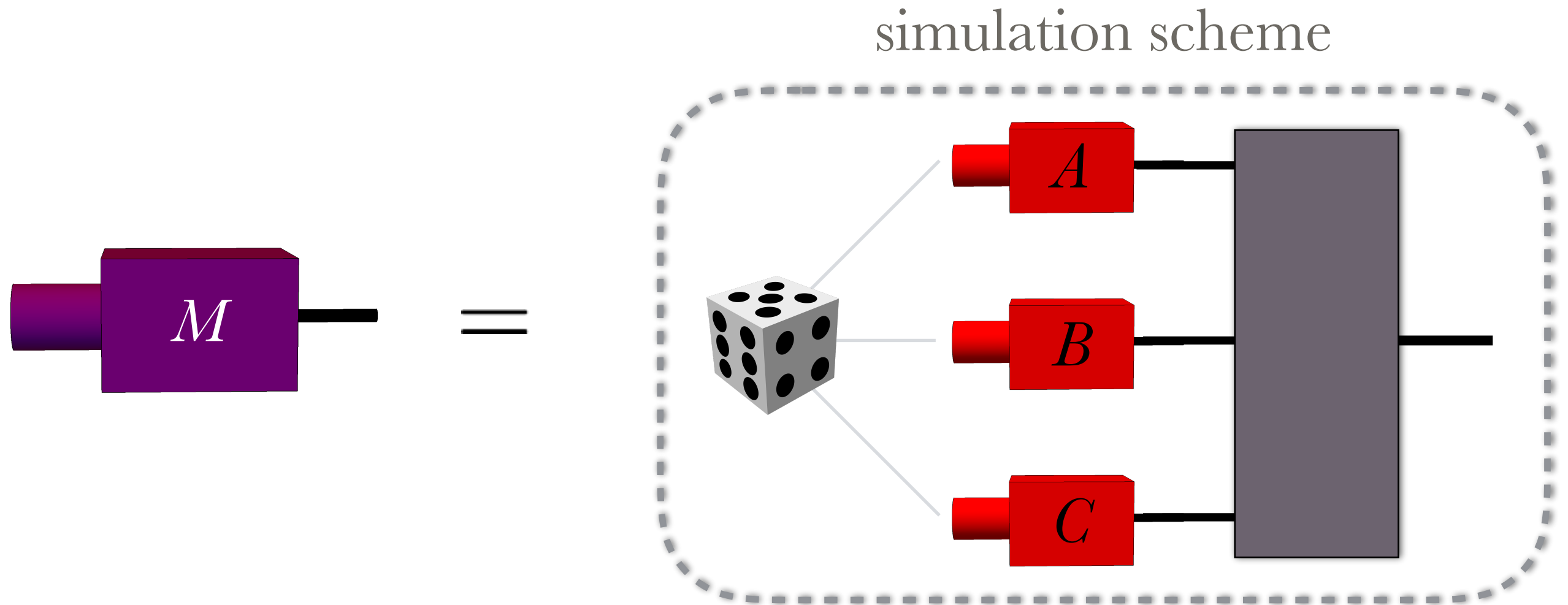
In a Galois connection  $\tau\sigma$  and  $\sigma\tau$  are closure maps.

Further,  $\tau\sigma\tau = \tau$  and  $\sigma\tau\sigma = \sigma$ .

# simulation closure



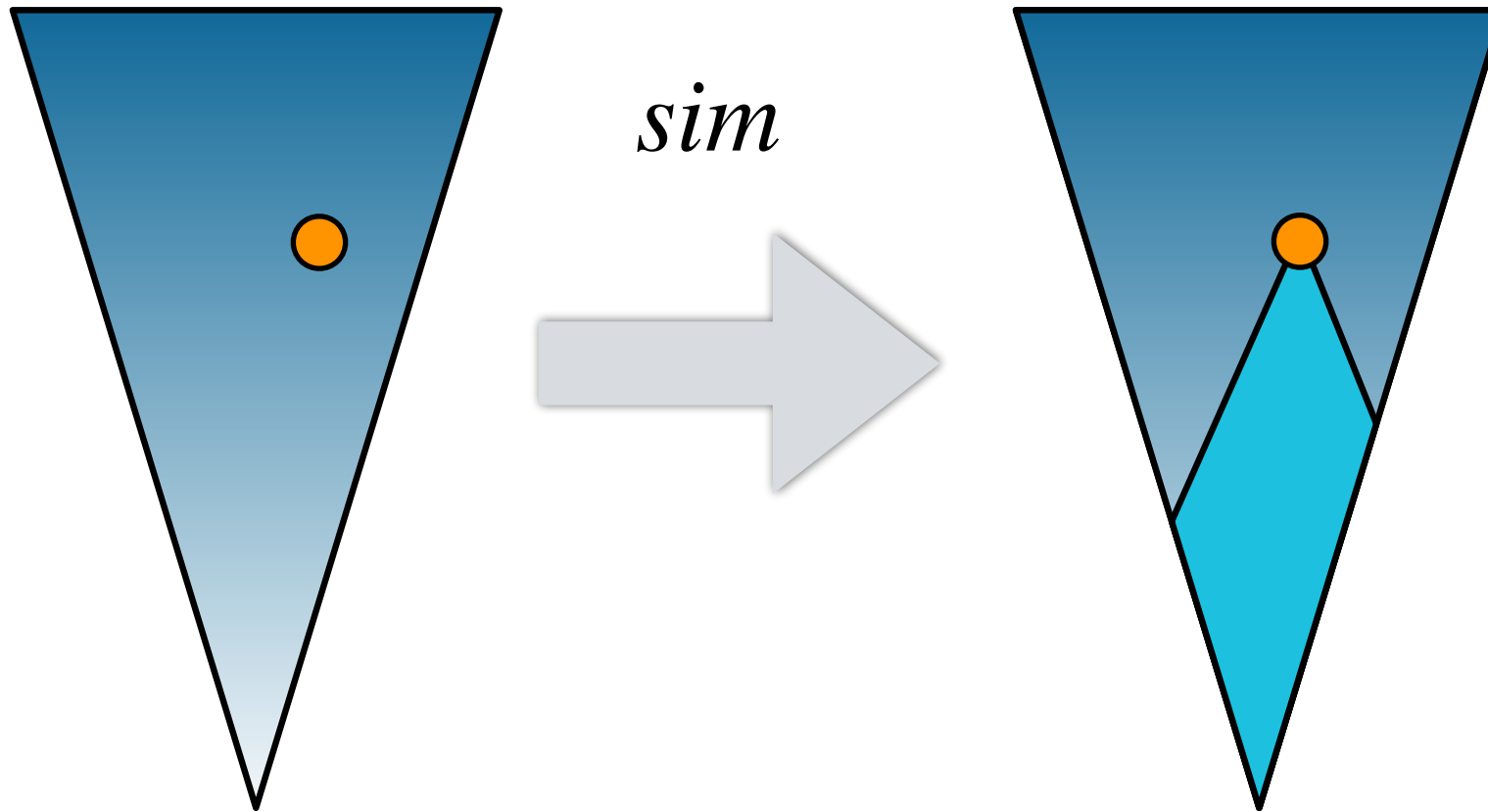
# simulation closure



$\text{sim}(\{A, B, C\}) = \{ \text{all observables that can be simulated from } A, B \text{ and } C \text{ with some randomization and post-processing} \}$

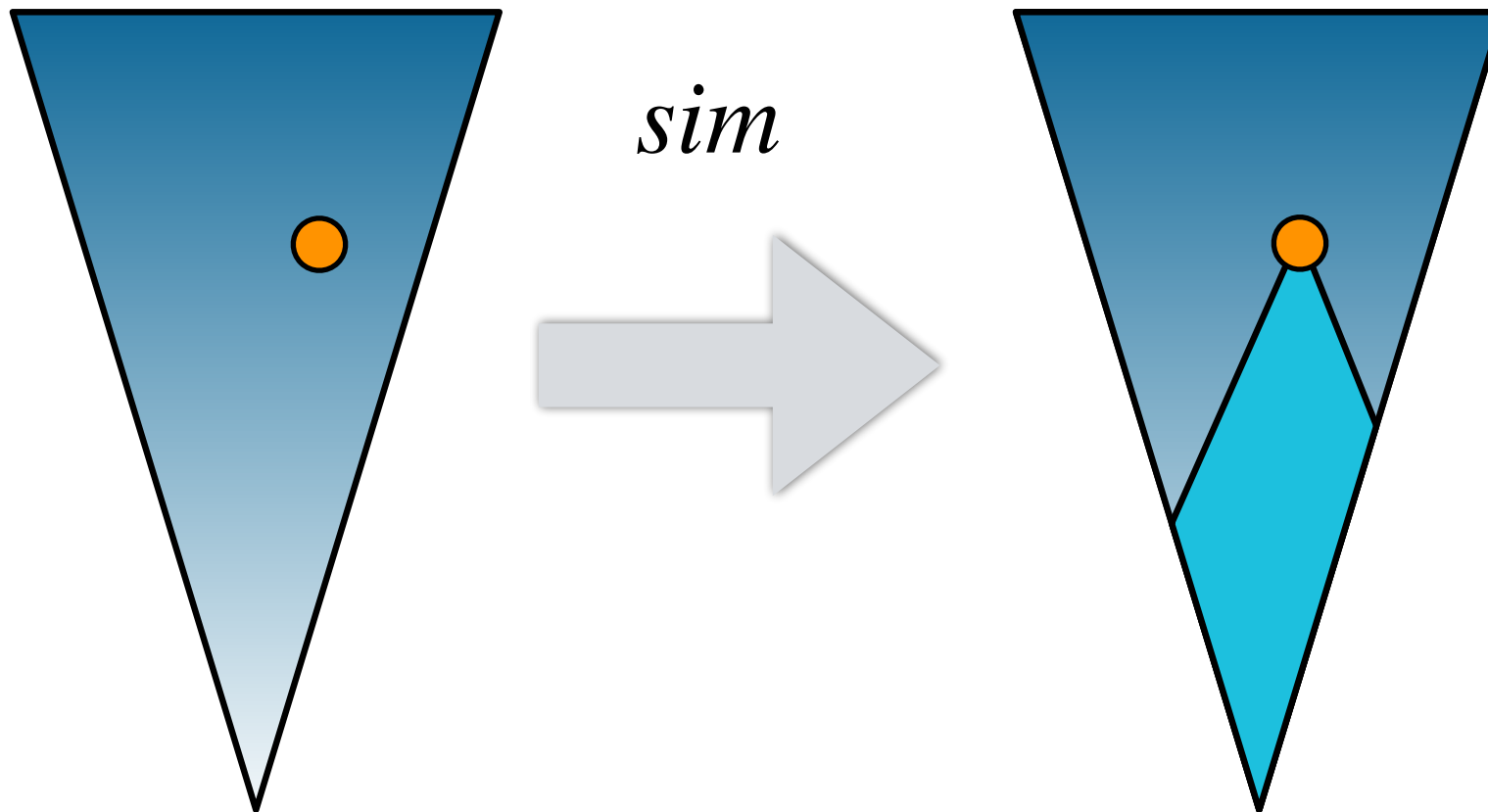
# simulation closure

$$\textit{sim}(\{A\}) = \downarrow A$$



# simulation closure

$$\textit{sim}(\{A\}) = \downarrow A$$



$$\textit{sim}(\tau(Y)) = \tau(Y)$$

# simulation closure

$$\tau\sigma(\{A\}) = \textit{sim}(\{A\}) = \downarrow A$$

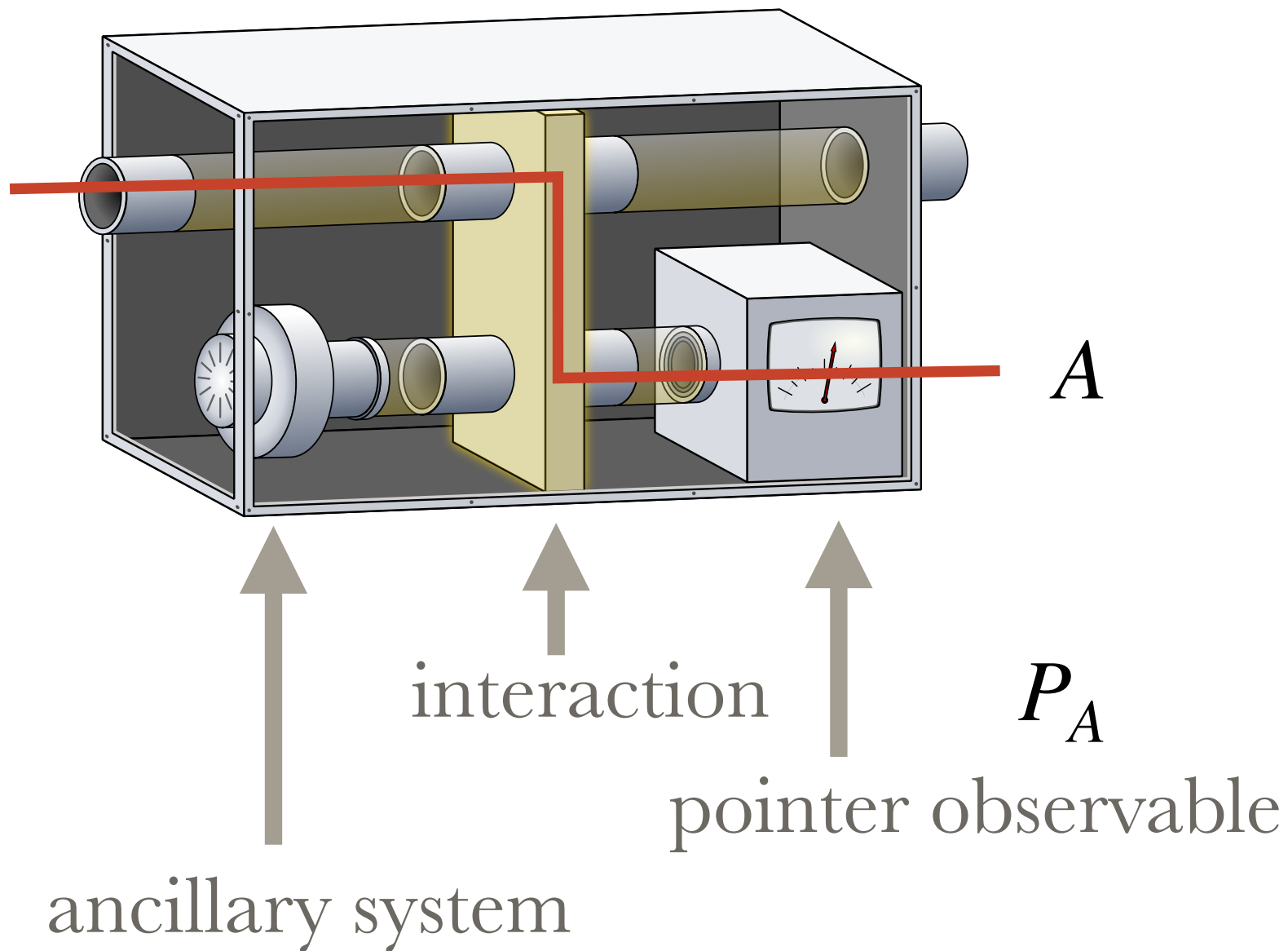
# simulation closure

$$\tau\sigma(\{A\}) = \textit{sim}(\{A\}) = \downarrow A$$

$$\tau\sigma(X) \supseteq \textit{sim}(X)$$

# physical interpretation of $\tau\sigma$

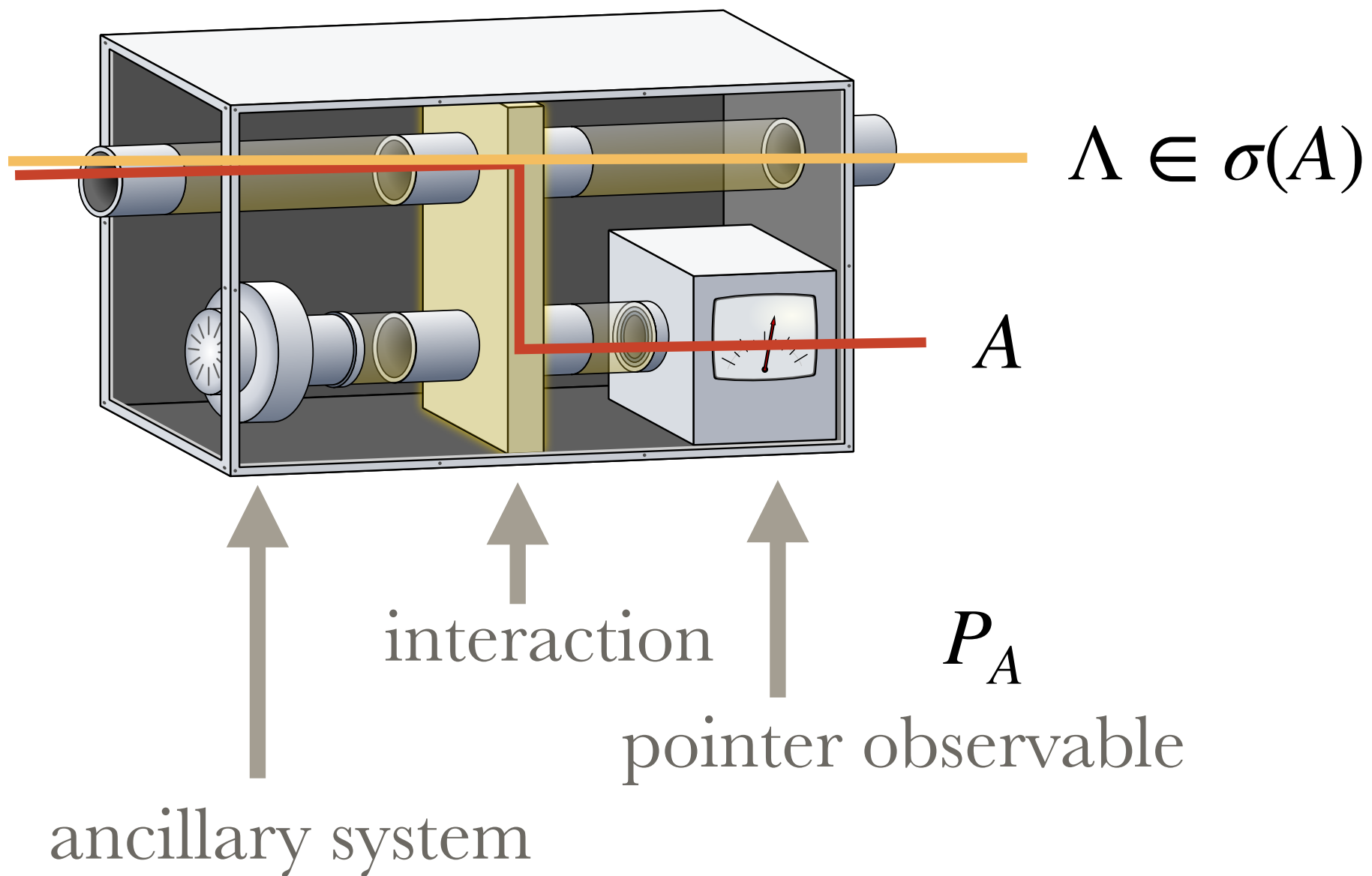
realization of  $A$





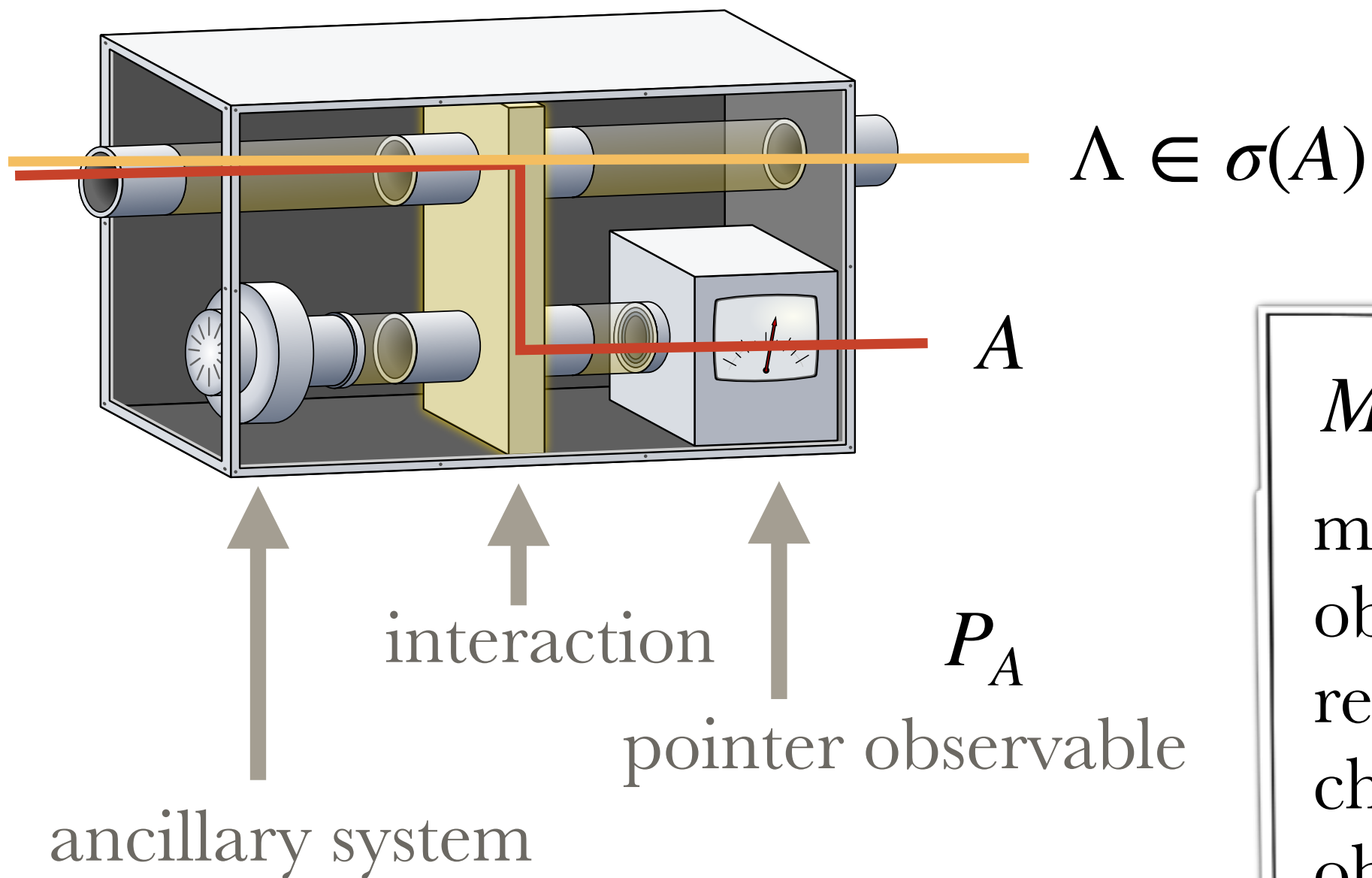
# physical interpretation of $\tau\sigma$

realization of  $A$



# physical interpretation of $\tau\sigma$

realization of  $A$

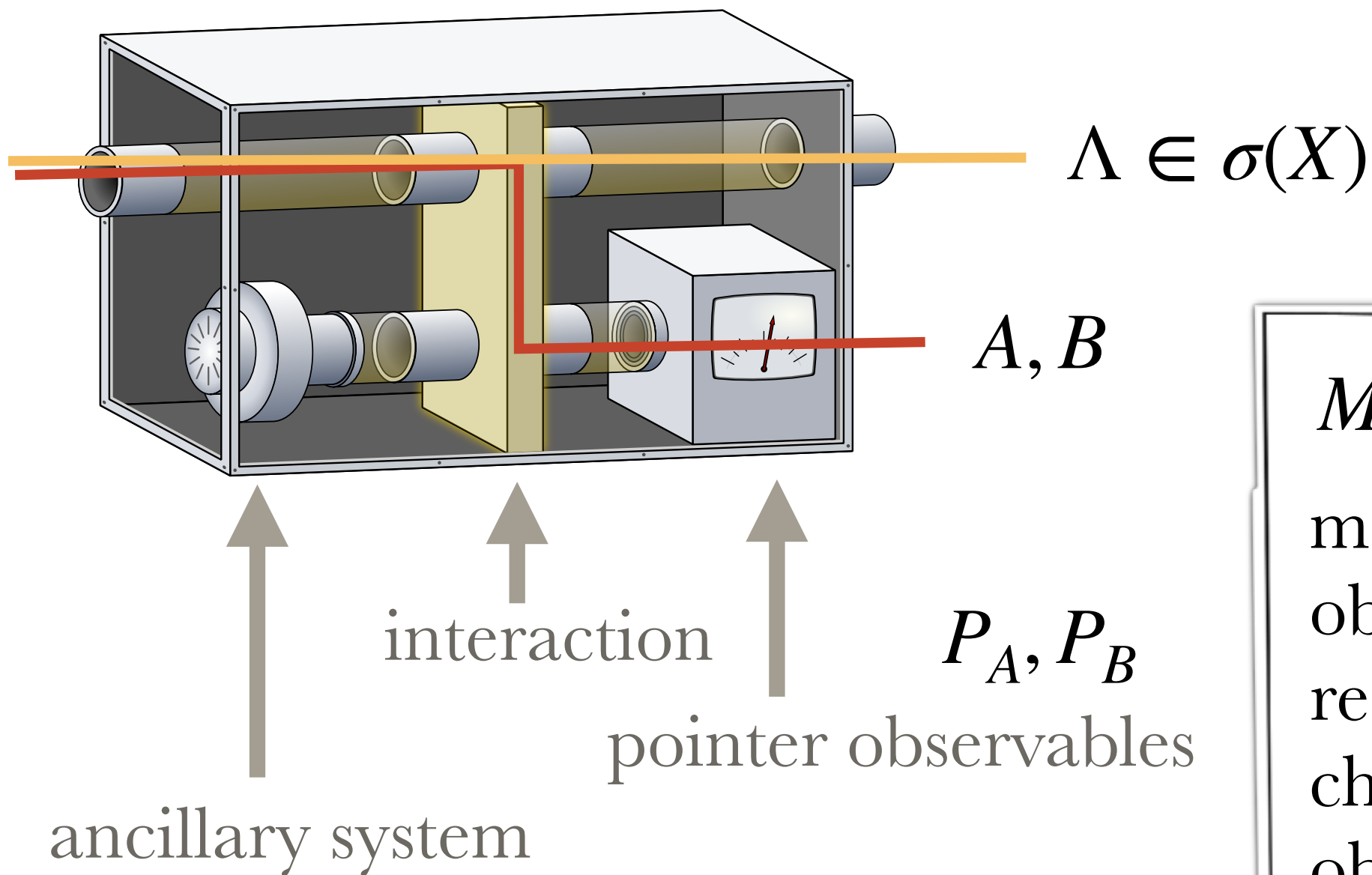


$$M \in \tau\sigma(A)$$

means that  $M$  can be obtained in *all* realizations of  $A$  by changing the pointer observable

# physical interpretation of $\tau\sigma$

realization of  $X = \{A, B\}$



$$M \in \tau\sigma(X)$$

means that  $M$  can be obtained in *all* realizations of  $X$  by changing the pointer observable

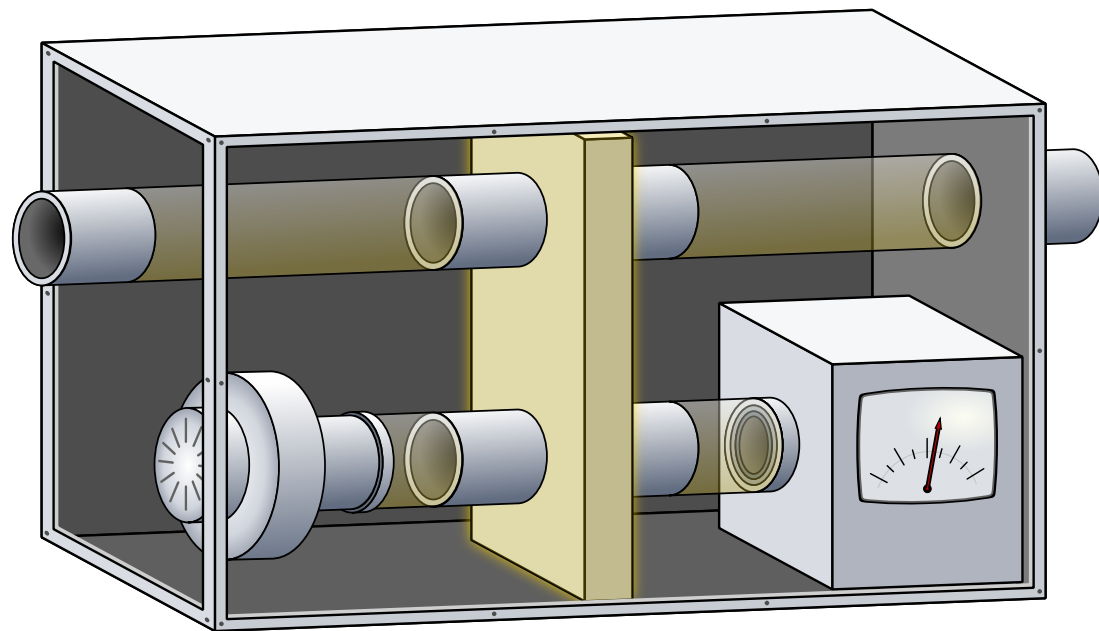
# physical interpretation of $\tau\sigma$

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$\tau\sigma(X)$  is the “information leak” required to implement  $X$

**Example:** it is possible that  $\tau\sigma(\{A, B\}) = O$



$\sigma(\{A, B\}) = [\text{discard-prepare}]$

pointer observables

$$P_A = A, P_B = B$$

interaction  $U(\psi \otimes \varphi) = \varphi \otimes \psi$

# physical interpretation of $\tau\sigma$

$\tau\sigma(X)$  is the “information leak” required to implement  $X$

**Example:** it is possible that  $\tau\sigma(\{A, B\}) = O$

However,  $\text{sim}(X) \neq O$  for any countable subset  $X$

# physical interpretation of $\tau\sigma$

$\tau\sigma(X)$  is the “information leak” required to implement  $X$

## Example:

$$E(1) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad E(2) = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad E(3) = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$A(1) = E(1) + E(2)$$

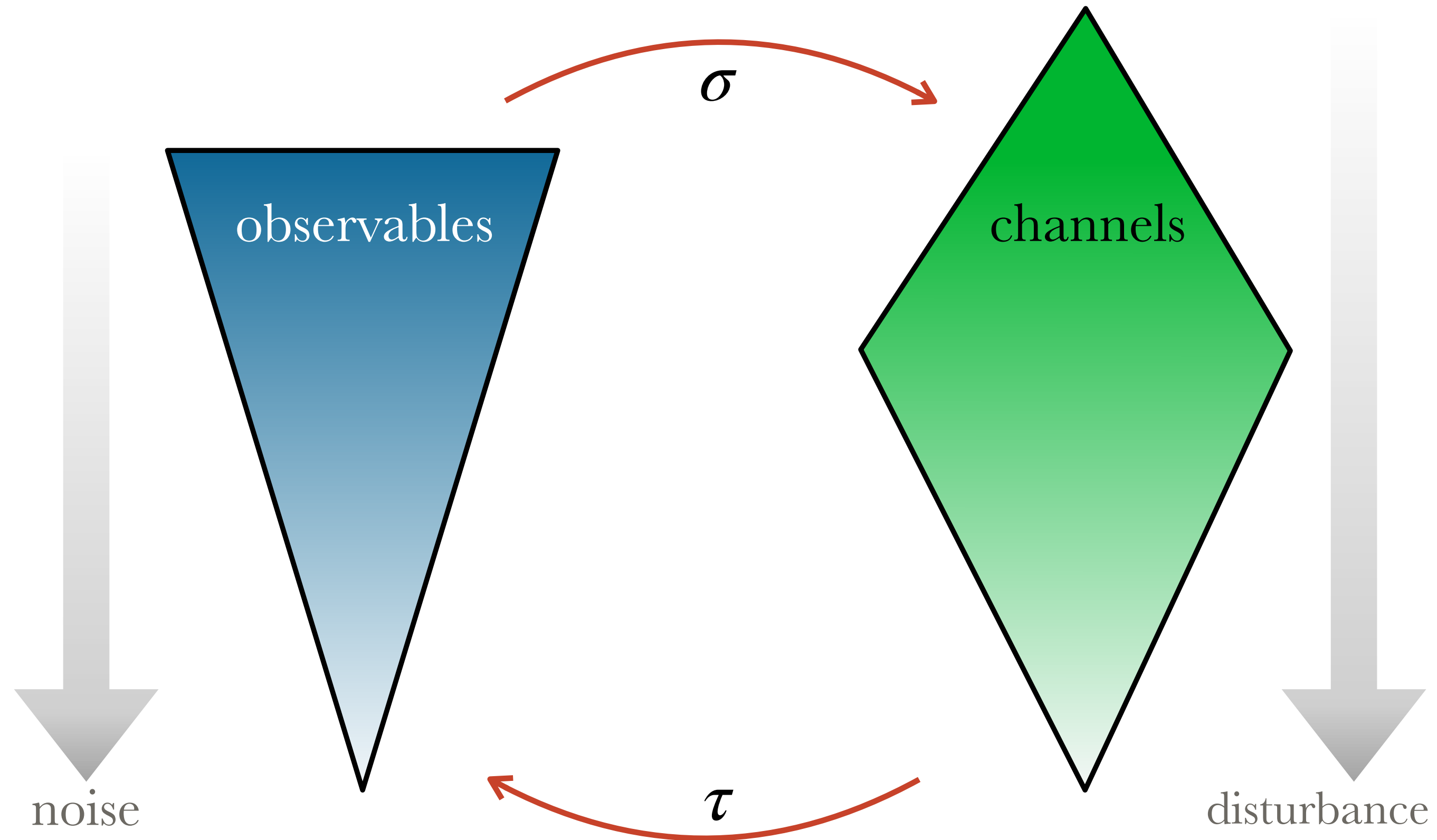
$$B(1) = E(1)$$

$$A(2) = E(3)$$

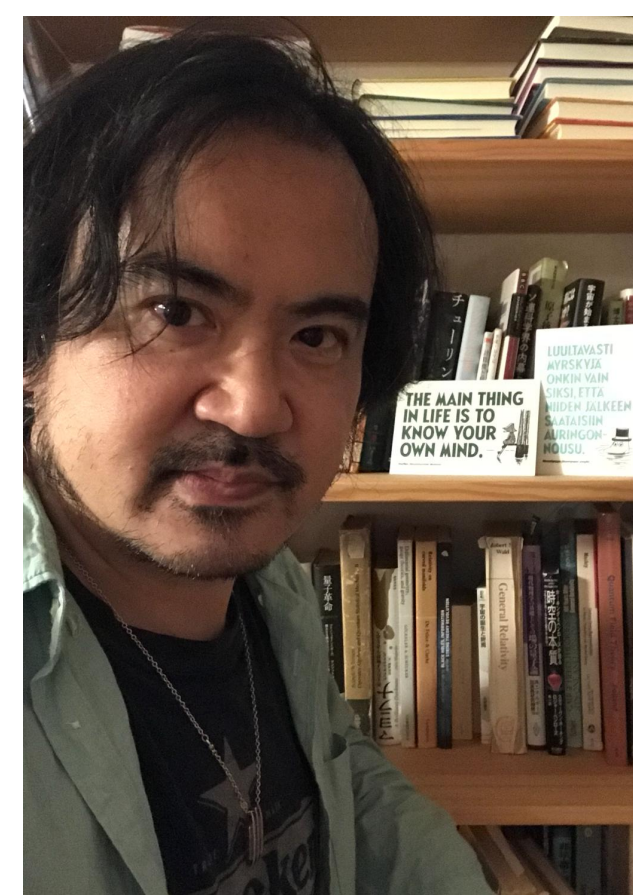
$$B(2) = E(2) + E(3)$$

$$\tau\sigma(\{A, B\}) = \downarrow E \neq \text{sim}(\{A, B\})$$

# Galois connection







- TH and **Takayuki Miyadera** : Qualitative noise-disturbance relation for quantum measurements, 2013
- TH and **Takayuki Miyadera** : Universality of sequential quantum measurements, 2015
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- **Sergey Filippov**, TH and **Leevi Leppäjärvi** : Simulability of observables in general probabilistic theories, 2018

- **Claudio Carmeli**, TH, **Takayuki Miyadera**, **Alessandro Toigo** : Noise-Disturbance Relation and the Galois Connection of Quantum Measurements, 2019